Agendas in Legislative Decision-Making*

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Abstract

Despite the wide variety of agendas used in legislative settings, the literature on sophisticated voting has focused on two formats, the so-called Euro-Latin and Anglo-American agendas. In the current paper, I introduce a broad class of agendas whose defining structural features, history-independence and persistence, are common in legislative settings. I then characterize the social choice rules implemented by sophisticated voting on agendas with these two features. I also characterize the rules implemented by more specialized formats (called priority agendas and convex agendas) whose structure is closely related to the prevailing rules for order-of-voting used by legislatures. These results establish a clear connection between structure and outcomes for a wide range of legislative agendas.

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1 Introduction

An agenda is a mechanism for collective decision-making that specifies a sequence of "yea" (yes) or "nay" (no) questions. Each successive question, to be decided by majority vote, forecloses some options until only a single alternative remains. In legislative settings, agendas are used to decide almost every issue. Dating back to the work of Black (1948, 1958) and Farquharson (1969), the goal has been to understand how the structure of the agenda shapes the legislative outcome when legislators behave in a sophisticated (or strategic) fashion.

Since Farquharson, the literature has focused on two formats, called Euro-Latin and Anglo-American agendas, that arise in legislative settings. Figure 1 below illustrates both formats for the case of three alternatives.\(^1\) On a Euro-Latin agenda (left), the voters consider one alternative at a time, ultimately selecting the first to be approved by a majority. On an Anglo-American agenda (right), the voters compare two alternatives at a time, with the majority winner progressing to the next stage and the loser being eliminated. Ultimately, the alternative selected is the one that survives this sequential process of pairwise comparison.

![Diagram of Euro-Latin and Anglo-American agendas](image)

**Figure 1:** Left: a Euro-Latin agenda on three alternatives. Right: an Anglo-American agenda on three alternatives.

While Farquharson’s analysis did not go beyond agendas with three alternatives, later work characterized the sophisticated voting outcomes for Euro-Latin and Anglo-American agendas of any size.\(^2\) Miller (1977, 1980) showed that Euro-Latin agendas lead to outcomes within the *top cycle* of the majority relation while Banks (1985) showed that Anglo-American agendas lead to outcomes within a subset of the more restrictive *uncovered set*.\(^3\) More recently, Apesteguia, Ballester, and Masatlioglu (2014) showed how the outcome implemented by each format co-varies with the profile of voter preferences and the set of feasible alternatives.

In the literature, the focus on Euro-Latin and Anglo-American agendas is usually justified by the assertion that these formats approximate the legislative process in civil law and common law jurisdictions (Miller, 1977, 1980).

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\(^1\)The names for these formats are not standard. Some follow Farquharson, who referred to Euro-Latin agendas as *successive agendas* and Anglo-American agendas as *amendment agendas*. Black referred to the latter as *ordinary committee procedure*.

\(^2\)For real-world examples of both formats with more than three alternatives, see Ladha (1994, p.60) and Senti (1998, p.16).

\(^3\)In the literature, this set is commonly known as the *Banks set*. The top cycle, uncovered set, and Banks set are examples of *tournament solutions*. For an overview of the vast literature on this topic, see Laslier (1997) or Brandt et al. (2016).
Ordeshook and Schwartz (1987) raised serious doubts about this view. Taking into account a variety of real-world examples, they concluded that legislative agendas regularly depart from the Euro-Latin and Anglo-American formats. Their conclusion is supported by a variety of other surveys and case studies (Bach, 1983; Sullivan, 1984; Krebs and Rivers, 1990; Calvert and Fenno, 1994; Miller, 1995; Volden, 1998; Schwartz, 2008). The practical implication is that legislative agendas can lead to policy outcomes different from those associated with Euro-Latin and Anglo-American agendas. This is troubling. Agendas play a crucial role in legislative decision-making. Without a clear understanding of what outcomes they induce, one cannot begin to address some of the most basic questions in political economy or public economics.

In the current paper, I characterize the outcomes implemented by a broad range of legislative agendas. To do so, I abstract away from the details of legislative procedure and focus on the emergent "procedural structure" (Sullivan, 1984). The simple agendas that I define are distinguished by two structural features: history-independence, which stipulates that the question posed at any stage can only depend on the alternatives not yet eliminated from consideration; and, persistence, which stipulates that "safe" alternatives (that do not risk elimination) at a given stage can only be tested after all questions related to the "contested" alternatives (that do risk elimination) have been settled. Both features are common in practice. Only agendas with procedural questions seem to violate history-independence; and only agendas that provide for parallel consideration of a bill and a substitute bill (like those sometimes used by US Congress) seem to violate persistence.

My main contribution is to determine what decision rules are implemented by simple agendas: as one varies the profile of voter preferences or the feasible set of alternatives, how does the sophisticated voting outcome change? Theorem 1 shows that two conditions, called issue splitting and the independence of losing alternatives, characterize implementation by simple agenda. The first condition, which weakens Plott's (1973) path independence, stipulates that the outcome can be determined by splitting the issue into two subsets of alternatives. In turn, the second condition, which weakens the independence of irrelevant alternatives (Chernoff, 1954; Radner and Marschak, 1954), stipulates that the removal of an alternative without any majority appeal (called the Condorcet loser) cannot affect the outcome.

I also characterize implementation by some more specialized formats that arise in legislative settings. Theorem 2 shows that Euro-Latin and Anglo-American agendas differ from other simple agendas by the way that they marginalize or discriminate against certain alternatives. For Anglo-American agendas, every issue includes one alternative that is chosen only when it has majority appeal over every alternative (i.e., it is the Condorcet winner). For Euro-Latin agendas, every issue includes two such alternatives. By highlighting the fundamental similarities between the two formats, these characterizations stand in contrast to the characterizations given Apesteguia et al., which instead highlight some key differences.

The important role played by marginalization extends to formats whose structure is related to the order-of-voting rules typically used in legislative settings—specifically priority agendas, whose sequential structure is

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4 The notable outlier is Rasch (2000), who concluded that Euro-Latin and Anglo-American agendas are dominant. However, his study was “not based on a close inspection of voting practices” and did not show “how stringently the two procedures are applied in day-to-day proceedings” (p.8). For further discussion of Rasch’s methodology, see Schwartz (2008, p.368).

5 The Online Appendix (https://sites.google.com/site/smhoran/TE-Appendix.pdf) elaborates on the formal connection.
related to the rule of precedence used by Anglo-American jurisdictions; and convex agendas, whose structure is related to the extremeness rule favored by Euro-Latin jurisdictions. (While convex agendas were previously considered by Kleiner and Moldovanu (2017), the current paper is the first to consider priority agendas. 6) Theorem 3 shows that priority agendas are distinguished from other simple agendas by the fact that they marginalize some alternative for every issue. In turn, Theorem 4 shows that convex agendas are distinguished by the fact that they only marginalize an alternative to facilitate the choice of another.

I conclude the paper by highlighting the connection between simple agendas and May’s (1952) desiderata for voting rules. Theorem 5 shows that every rule implemented by simple agenda is positively responsive: the outcome remains unchanged when it improves in terms of voter preferences. Since agendas also treat voters symmetrically (anonymously), every rule implemented by simple agenda satisfies two of May’s criteria. However, his third criterion, which requires alternatives to be treated symmetrically (neutrally), cannot be satisfied by any agenda containing more than two alternatives. 7 Theorems 2 to 4 sharpen this observation—by characterizing ways that a range of agenda formats used in legislative settings treat alternatives asymmetrically.

Related Literature: The main strand of the sophisticated voting literature has focused on a narrow range of agendas. Indeed, almost all of the papers (including e.g., recent work by Gershkov et al., 2017; or Barberà and Gerber, 2018) are concerned with Euro-Latin and Anglo-American agendas specifically. Only a handful of papers consider other agenda formats (Banks, 1989; Coughlan and Le Breton, 1999; Fischer et al., 2011; Iglesias et al., 2014; Schwartz, 2008). A much smaller strand of the literature is concerned with general conditions that are necessary (McKelvey and Niemi, 1978; Moulin, 1986; Srivastava and Trick, 1996) or necessary and sufficient (Horan, 2013) for implementation by agenda. However, the results in these papers are largely non-constructive. So, they say little about what kinds of outcomes can be achieved with specific agenda formats.

The current paper bridges the gap between these two strands of the literature by characterizing the relationship between form and function for a wide range of agendas used in legislative settings. While the prior work on this issue is quite limited, two papers are worth mentioning. The first is the paper of Ordeshook and Schwartz (1987), who proposed a taxonomy of agenda features (which was later extended by Miller, 1995). 8 While I do not rely on their taxonomy, my work is motivated by the same desire to abstract away from institutional details and focus on the structural features of agendas that arise legislative settings. The other relevant paper is Apesteguia et al. (2014), who introduced the decision rule framework that I adopt in the current paper. From an implementation standpoint, their framework is unusual because it allows the voter preferences and the set of alternatives to vary. While this extra degree of freedom does not affect the scope of implementable rules (see Remark 1), it does simplify the interpretation of the conditions for implementation. As a collateral benefit, the decision rule framework is also quite natural in applications.

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6 Convex agendas have also been studied by Gershkov et al., 2019; and Kleiner and Moldovanu, 2018.
7 More generally, it is only possible for a single-winner voting rule to treat both the voters and the alternatives symmetrically under strong restrictions on the number of voters and alternatives. For further details, see Moulin (1988, p.253).
8 While Ordeshook and Schwartz also characterize the range of outcomes associated with several agenda formats (à la Banks and Miller), they do not characterize the outcomes implemented by any of these formats (à la Apesteguia et al.).
2 Simple agendas

In this section, I define agendas in general terms before describing the two structural features that define simple agendas. I conclude by presenting several examples of simple agendas that arise in legislative settings.

2.1 Agendas

The universe of social alternatives is a finite set $X$ such that $|X| \geq 2$ and an issue $A$ is a non-empty subset of $X$. Letting $X$ denote the collection of all issues $A$ such that $|A| \geq 2$, an agenda is defined as follows:

Definition 1 An agenda $T_A$ on $A \in X$ is a finite binary tree such that:

(i) each terminal node is labeled by (a set consisting of) one alternative in $A$;
(ii) each alternative in $A$ labels one or more terminal nodes; and,
(iii) each non-terminal node is labeled by the set of alternatives that label its two successors.

To simplify, I omit the subscript for an agenda on the universal issue $X$ (writing $T$ instead of $T_X$).

The Appendix contains a primer of the graph theory terminology used above and elsewhere in the paper.

An agenda defines a game tree where each outcome (terminal node) represents a social alternative and each stage game (non-terminal node) represents a simultaneous majority vote between the two subgames that follow it. In legislative settings, every vote addresses a yea or nay question. Features (i) and (ii) of Definition 1 ensure that: every sequence of questions leads to an outcome; and every outcome results from some sequence of questions. Feature (iii) is a labeling convention: it identifies each node with the outcomes that are reachable from it.\textsuperscript{9} It is worth emphasizing that no aspect of my analysis depends on this convention. It serves only to simplify the definition of the agenda classes that I consider.

In the sequel, I depart from Figure 1 and omit the edge labels from agenda diagrams. Instead, I follow the convention that, at any non-terminal node, the left subgame represents majority support for yea while the right represents majority support for nay. As in Figure 1, I also omit the set brackets for the terminal nodes. In fact, I omit the brackets for singleton sets whenever doing so causes no confusion.

2.2 Simple agendas

Two structural features define the agendas that I consider in the sequel. The first specifies that, for all nodes leading to the same potential outcomes, the agenda poses the same question. Given an agenda, let $\ell(q)$ denote the label of a node $q$; and let $q_y$ (yea) and $q_n$ (nay) denote the two successors of a non-terminal node $q$. Then, an agenda is history-independent if, for all pairs of non-terminal nodes $q$ and $\bar{q}$ such that $\ell(q) = \ell(\bar{q})$,

$$\{\ell(q_y), \ell(q_n)\} = \{\ell(\bar{q}_y), \ell(\bar{q}_n)\}.$$\textsuperscript{9}

\textsuperscript{9}This convention follows the Farquharson-Miller approach rather than the Ordeshook-Schwartz approach (see Schwartz, 2008).
In other words, the structure of the agenda below \( q \) depends on the set of reachable alternatives \( \ell(q) \) but not the sequence of questions leading up to \( q \). As a result, there is no confusion in referring to a node \( q \) of a history-independent agenda by its label \( \ell(q) \). To simplify, I follow this convention in the sequel.\(^{10}\)

The second feature specifies that the agenda cannot address new issues until contested issues have been resolved. For a node \( q \), let \( u(q) \equiv \ell(q_y) \cap \ell(q_n) \) denote the set of uncontested outcomes that face no risk of elimination at \( q \). Conversely, let \( c(q) \equiv \ell(q) \setminus u(q) \) denote the set of contested outcomes that do risk elimination at \( q \).\(^{11}\) Then, an agenda is persistent if, for every node \( q \) such that \( u(q) \neq \emptyset \) and each terminal node \( t \) below \( q \), there is a non-terminal node \( q^t \) between \( q \) and \( t \) (potentially \( q \) itself) such that

\[
u(q) \in \{\ell(q_y^t), \ell(q_n^t)\}.
\]

The two possibilities associated with this condition are illustrated below: either some node between \( q \) and \( t \) is labeled \( u(q) \) (left); or the sibling of some node between \( q \) and \( t \) is labeled \( u(q) \) (right).

The idea is that one of the answers to question \( q^t \) resolves the “live” issue \( c(q) \) contested at \( q \). From that point on, the agenda only contests alternatives associated with the “new” issue \( u(q) \). By definition, none of the previous questions (between \( q \) and \( q^t \)) contests alternatives in \( u(q) \) (see Remark 5 of the Appendix).

**Definition 2** An agenda is **simple** if it is history-independent and persistent.

My focus on simple agendas is motivated by the prevalence of history-independence and persistence among legislative agendas. Below, I give some examples of agendas, drawn from a range of different legislative settings, that exhibit these two features. Before turning to these examples, it is worth giving a broader sense of the basis for history-independence and persistence in the rules of legislative procedure.

History-independence relates to the fact that legislative rules for agenda-building are generally prospective: starting from any point, the prescribed structure of the agenda only depends on the set of pending proposals.

\(^{10}\)See, in particular, Definitions 6 and 7 below.

\(^{11}\)As a matter of convention, let \( u(t) \equiv \emptyset \) and \( c(t) \equiv \ell(t) \) for every terminal node \( t \).
The only notable exception relates to procedural motions that do not necessarily eliminate any outcomes. In a division of the question motion, for instance, the issue is whether each part of the bill should be put to vote separately.\textsuperscript{12} If the division motion is defeated, then the same set of outcomes remain feasible. Since the motion cannot be reconsidered, this introduces history-dependence into the agenda.

Persistence can, in part, be explained by the admissibility rules imposed in legislative settings (Sullivan, p.35). Many jurisdictions require that a new proposal must be “in order” before it can be introduced for debate. Some jurisdictions also require that a new proposal must be “germane” to one of the pending proposals.\textsuperscript{13} Broadly speaking, these requirements ensure that new proposals are introduced (and, consequently, voted on) only after a consensus on existing proposals has been sufficiently established.

To ensure that legislative agendas are persistent, the rules for order-of-voting on proposals play an even more significant role. Most legislatures follow one of two schemes: the formalistic rule of precedence favored by Anglo-American jurisdictions; or the substantive extremeness rule favored by Euro-Latin jurisdictions (see Rasch, 2000, p.15). As I explain in Section 4, both schemes tend to produce persistent agendas.

2.3 Examples

Example 1 When two amendments are proposed to “perfect” a bill, the rule of precedence used by US Congress requires an up-or-down vote on the first amendment before the second can be recognizing. If the amendments are incompatible (in the sense that they propose conflicting modifications to the bill), then the second amendment cannot be recognized if the first is adopted. This leads to the following agenda.\textsuperscript{14}

\begin{align*}
Q1. & \quad \text{Shall the first amendment } a' \text{ to the bill } b \text{ be adopted?} \\
Q2. & \quad \text{If not, shall the second amendment } a'' \text{ to } b \text{ be adopted?} \\
Q3. & \quad \text{Shall the perfected version of the bill replace the status quo legislation } \emptyset ?
\end{align*}

This agenda, which combines elements of Euro-Latin and Anglo-American agendas, is simple.\textsuperscript{15} Clearly, it is

\textsuperscript{12}See e.g., House Rule XVI(5). For an agenda that includes such a division of a question, see Schwartz (2018, p.97).
\textsuperscript{13}See e.g., House Rule XVI(7). In contrast, the Senate Rules do not impose a germaneness requirement (Riddick, 1992, p.62).
\textsuperscript{14}Figure 5 of Ordeshook and Schwartz shows a similar agenda that can arise in Congress.
\textsuperscript{15}The procedure for perfecting the bill is Euro-Latin: first, the question is whether $a'$ should be approved; and, if not, whether $a''$ should be approved. However, the procedure for adopting the bill is Anglo-American: the last question always pits the perfected bill against the status quo, which is a standard feature in many Anglo-American jurisdictions (see Rasch, Table 2).
history-independent: each node has a unique label. It is also persistent: the only alternative uncontested at any node is the status quo $\emptyset$, which is ultimately contested by the final question.

**Example 2** In many legislative settings, it is conventional to consider the sections of a (potentially lengthy) proposal “in seriatim” (see Robert, pp.276-278). If the proposal consists of new bylaws, for instance, then the practice is to vote on the bylaws one at a time.\(^{16}\) The agenda depicted below serves to illustrate.

\[\begin{align*}
Q1. & \text{ Shall the first bylaw } b_1 \text{ be adopted?} \\
Q2. & \text{ Shall the second bylaw } b_2 \text{ be adopted?}
\end{align*}\]

This is an example of a *knockout agenda*, so called because each alternative appears at only one terminal node (and can, thus, be “knocked out” by any vote). Since the label of each node is unique, a knockout agenda must be history-independent. Since there are no uncontested alternatives at any node, it must also be persistent.

**Example 3** The process for deciding among conflicting floor proposals in Swiss parliament requires a sequence of elimination votes “first on the proposals that differ the least from each other in content, working through the proposals until those that differ the most are reached.”\(^{17}\) To illustrate, suppose that four amendments $a_1, \ldots, a_4$ (ordered in terms of similarity) are proposed, with the middle two amendments being most similar.

\[\begin{align*}
Q1. & \text{ Shall amendment } a_2 \text{ be adopted over the next most similar amendment } a_3? \\
Q2. & \text{ Shall the winner of Q1 be adopted over the next most similar amendment?} \\
Q3. & \text{ Shall the winner of Q2 be adopted over the remaining amendment?}
\end{align*}\]

\(^{16}\text{Plott and Levine (1976) call this type of agenda a *bill-by-bill agenda*.}\)

\(^{17}\text{See Article 79.2 of the *Loi sur le Parlement*.}\)
This agenda is history-independent: the only nodes that share the same label occur in the last stage where there is no flexibility about the question to be asked. It is also persistent. To see this, first consider the alternatives \( \{a_1, a_4\} \) that are uncontested at the root. Since this set labels a successor of both nodes at the second stage (in bold), the agenda is persistent at the root. The same is true for each node in the second stage. The uncontested alternative \( a_4 \) at the left-hand node labels a terminal node below both successors of that node. Likewise, \( a_1 \) labels a terminal node below both successors of the right-hand node.

### 3 Implementation by simple agenda

In this section, I define implementation by agenda before focusing the analysis on simple agendas—showing that two natural conditions characterize the decision rules implemented by agendas in this class.

#### 3.1 Implementation

Let \( N \) denote the finite set of voters. For simplicity, suppose that \(|N|\) is odd and \(|N| \ge |X|\). A profile of voter preferences \( P = (P_i)_{i \in N} \) is an \(|N|\)-tuple of linear orderings \( P_i \) over \( X \). A decision problem is pair \((P, A)\). Letting \( P \) denote the collection of all profiles, a decision rule is a mapping \( v : P \times X \rightarrow X \) such that \( v(P, A) \in A \) for all \((P, A) \in P \times X\). Thus, \( v \) prescribes an outcome for all combinations of issues and voter preferences.

Since my focus is the implementation of decision rules, it is necessary to adapt an agenda \( T \) on the universal issue \( X \) to every sub-issue \( A \subset X \). The most natural way to do this is to remove all of the terminal nodes labeled by infeasible alternatives (see Xu and Zhou, 2007; Horan, 2011; Bossert and Sprumont, 2013).

**Definition 3** Given an agenda \( T \) on \( X \), the pruned agenda \( T|_A \) on \( A \in X \) may be obtained as follows:

1. First, remove every terminal node of \( T \) that is labeled by an alternative \( x \in X \setminus A \).
2. Then, remove every node that has one successor, connecting its successor to its predecessor.
3. Finally, relabel every non-terminal node of the resulting tree to conform with Definition 1.

Like a single-elimination sports competition, the idea is that the infeasible alternatives in \( X \setminus A \) “forfeit” their place without otherwise modifying the structure of the agenda. To illustrate, consider the following agenda \( T \) on \( X = \{a, a', b, c, x\} \) and the pruned agenda \( T|_A \) on the subset \( A = \{b, c, x\} \):

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18The assumption that \(|N|\) is odd ensures that the majority relation is total and asymmetric. In turn, \(|N| \ge |X|\) ensures that every majority relation results from some preference profile. (See footnote 19 and the preceding discussion.)
Given an agenda $T$ on $X$, each pair $(T|_A; P)$ defines a complete information extensive-form game with voter preferences given by $P$ and outcomes in $A$. The natural solution concept for this type of game is sophisticated voting (Farquharson, 1969), which is based on the idea that voters are forward-looking. As it turns out, the unique sophisticated voting equilibrium outcome only depends on the preference of the majority. For $P \in P$, the majority relation $M_P$ between alternatives $x, y \in X$ is defined by:

$$xM_P y \text{ if } |\{i \in N : xP_i y\}| > |N|/2.$$ 

Since $|N|$ is odd, $M_P$ is a total (for distinct $x, y \in X$, $xM_P y$ or $yM_P x$) and asymmetric (for $x, y \in X$, not $xM_P y$ and $yM_P x$) binary relation on $X$. A relation with these features is usually called a tournament.\(^{19}\)

In any vote at the final stage of an agenda $T|_A$, every voter has a weakly dominant strategy to endorse her preferred alternative. So, in any vote at this stage, $M_P$ determines which alternative wins a majority. When deciding how to vote at the penultimate stage, the forward-looking voters discount the alternatives that will lose at the final stage, and again perceive the vote as a choice between two alternatives. So, $M_P$ also determines which option (yea or nay) wins a majority at this stage. By extending this reasoning back to the root of the agenda, one can use the majority relation $M_P$ to determine the sophisticated voting outcome of the game $(T|_A; P)$. As shown by McKelvey and Niemi (1978), this “backward induction” reasoning is equivalent to finding the dominance solvable (Moulin, 1979) outcome of the game $(T|_A; P)$.\(^{20}\) To formalize:

**Definition 4** For a game $(T|_A; P)$, the sophisticated voting outcome $SVO[T|_A; P]$ is defined as follows:

1. First, define $T^P_A(1) \equiv T_A$ to be the original agenda.
2. Then, for each $j > 1$, define the agenda $T^P_A(j + 1)$ from $T^P_A(j)$ as follows:
   - In each terminal subgame of $T^P_A(j)$, prune away the loser according to $M_P$; and,
   - Relabel the non-terminal nodes of the resulting binary tree to conform with Definition 1.

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\(^{19}\)McGarvey (1953) was the first to consider the problem of finding the minimum number of voters $|N|$ such that $\{M_P : P \in P\}$ coincides with the set of all tournaments on $X$. He showed that $|N| \geq |X|^2 - |X|$ is sufficient. Stearns (1959) tightened the bound to $|N| \geq |X| + 2$ and Fiol (1992) later improved Stearns’ bound to $|N| \geq |X| - \lfloor \log_2 |X| \rfloor + 1$.

\(^{20}\)The quotation marks (which I continue to use in the sequel) serve as a reminder that this is not technically backward induction. The problem is the absence of full information: each stage game involves simultaneous choices by all voters.
Finally, define $SVO[T_A; P] \equiv T^P_A(K)$ where $K$ is the smallest $j$ such that $T^j_A(j) = T^P_A(j + 1)$.

Having defined the solution concept, agenda implementation may then be defined as follows:

**Definition 5** A decision rule $v$ is implementable by agenda if there exists an agenda $T$ such that

$$v(P, A) = SVO[T_A; P]$$

for every decision problem $(P, A) \in P \times X$. In that case, the agenda $T$ implements the decision rule $v$.

Despite appearances, this formulation is no more general than the usual notion of implementation with a fixed issue $X$. To see this, consider a decision problem $(P, A)$ and let $P^A$ denote a profile that coincides with $P$ on $A$ except that, in each voter preference, the alternatives in $X \setminus A$ are placed (in a fixed order) below every alternative in $A$. This demotion is equivalent to pruning away the alternatives in $X \setminus A$:

**Remark 1** If a decision rule $v$ is implementable by agenda, then $v(P, A) = v(P^A, X)$ for all $(P, A) \in P \times X$.

In other words, the sub-issues actually play no role in the analysis of agenda implementation. Once the agenda-setter decides what to implement for the grand issue $X$, the outcomes for all sub-issues $A \subset X$ are determined.

### 3.2 Characterization

Two conditions are necessary and sufficient for implementation by simple agenda. The first stipulates that the outcome of any decision problem can be determined by “splitting up” the issue into two sub-issues. For a decision rule $v$, a pair of issues $(B, C) \subseteq X \times X$ defines a $v$-splitting of the issue $A \in X$ if:

1. $B \cup C = A$ so that $B$ and $C$ form an exact bi-cover of $A$;
2. $B \cap C \neq B, C$ so that $B$ and $C$ are non-nested; and,
3. $v(P, A) = v(P, \{v(P, B), v(P, C)\})$ for every profile $P \in P$.

The first condition stipulates that every issue can be split up in this way:

**Issue splitting (IS)** For every issue $A \in X$, there is a $v$-splitting.

While similar in spirit to Plott’s *Path independence*, this condition is weaker. Indeed, Plott’s condition imposes the requirement that the equality in (iii) must hold for all pairs $(B, C)$ that (i) form an exact bi-cover of $A$ even if $B$ and $C$ are nested (which conflicts with (ii) above). Issue splitting also weakens Apesteguia et al.’s *Division consistency* (called *Weak separability* by Xu and Zhou, 2007).\footnote{Formally, this condition may be stated as follows. For every issue $A \in X$, there exists a pair $(B, C) \in X \times X$ such that: (i') $B \cup C = A$; (ii') $B \cap C = \emptyset$; and, (iii') $v(P, D) = v(P, \{v(P, B \cap D), v(P, C \cap D)\})$ for each profile $P \in P$ and each $D \subseteq A$.}

The second condition states that the outcome is not affected by the presence of an unappealing alternative. Specifically, alternative $a \in A$ is the Condorcet loser for a decision problem $(P, A) \in P \times X$ if $xM_PA$ for all
A decision rule \( v \) is independent of the losers for the issue \( A \in X \) if: for all \( P \in P \) and \( a \in A \), \( v(P, A) = v(P, A \setminus a) \) if \( a \) is the Condorcet loser for \( (P, A) \).

Independence of losing alternatives\(^{23}\) (ILA) For every issue \( A \in X \), \( v \) is independent of the losers.

By comparison, the well-known Independence of irrelevant alternatives (IIA) imposes the much stronger requirement that the removal of any unchosen alternative keeps the outcome unchanged.\(^{24}\)

These two conditions characterize the decision rules that can be implemented by simple agenda. What is more, the simple agenda that implements the rule is unique; and, its structure can be inferred from the outcomes of \( v \) for profiles, called Condorcet triples, where the majority relation forms a cycle on three alternatives.

Theorem 1 (Necessary and sufficient conditions) A decision rule \( v \) is implementable by simple agenda if and only if it satisfies Issue splitting and Independence of losing alternatives. (Uniqueness) For every decision rule \( v \) that satisfies these two properties, there is a unique simple agenda \( S^v \) that implements \( v \). What is more, the structure of the agenda \( S^v \) is fully determined by the outcomes of \( v \) on Condorcet triples.

ILA is necessary for implementation by all agendas (not just simple agendas).\(^{25}\) This is because “backward induction” is unaffected by pruning away the Condorcet loser (see Remark 1 above). However, as the next example shows, Issue splitting is not generally necessary. To simplify, let \( P_{xyz} \) denote a Condorcet triple where \( x \) is majority preferred to \( y \), \( y \) is majority preferred to \( z \), and \( z \) is majority preferred to \( x \).

Example 4 The rule implemented by the agenda \( T \) in Figure 2 (satisfies IIA but) violates IS. For the Condorcet triple \( P_{xbc} \), a majority of voters prefer \( x \) to the alternative \( b \) chosen for \( (P_{xbc}, A) \). So, \( x \) cannot be paired with \( b \) in the splitting of \( A \). By similar reasoning about \( (P_{xcb}, A) \), \( x \) cannot be paired with \( c \). This leaves \((x, \{b, c\})\) as the only potential splitting of \( A \). However, this requires \( x \) to be chosen for \( (P_{xbc}, A) \) and \( (P_{xcb}, A) \).

For the sufficiency and uniqueness portions of Theorem 1, the key is to show that Issue splitting and Independence of losing alternatives imply that every issue has a unique splitting (Claim 5 of the Appendix). One can then define an agenda \( S^v \) that sub-divides the issue \( \ell(q) \) at any node \( q \) according to its unique splitting. To establish sufficiency, it only remains to show that the agenda \( S^v \) is simple and implements \( v \). The uniqueness of the implementing agenda follows, in turn, from the uniqueness of the splittings.

To get a better sense of the role played by Issue splitting, consider what happens when this condition is strengthened to Plott’s Path independence. For decision rules, Plott’s condition implies that, for each profile

\(^{22}\)To ensure that this identity is well-defined in the case where \( |A| = 2 \), let \( v(P, \{x\}) \equiv x \) for all \( x \in X \).

\(^{23}\)Apesteguia et al. call this condition Condorcet loser consistency (a name which usually refers to the requirement that the Condorcet loser cannot be chosen). To avoid potential confusion with this weaker property, I depart from their nomenclature.

\(^{24}\)While IIA was first proposed for individual choice, similar conditions have also been considered for voting (Fishburn, 1974; Young, 1995; Ching, 1996). To be clear, the condition is distinct from Arrow’s (1950) IIA condition for social choice (Ray, 1973).

\(^{25}\)Nonetheless, ILA is independent from IS. To see this, consider the decision rule \( v \) on \( X := \{x_1, x_2, x_3\} \) that selects: the majority preferred alternative between \( x_1 \) and \( x_2 \) when both are available; and \( x_1 \) on \( \{x_1, x_2\} \). Since \( \{\{x_1, x_2\}, \{x_2, x_3\}\} \) splits \( \{x_1, x_2, x_3\} \), \( v \) satisfies IS. To see that it violates ILA, consider a profile \( P \) where \( x_3 \) is the Condorcet winner on \( X \). If \( v \) satisfies ILA, then \( v(P, \{x_1, x_2, x_3\}) = \ldots = x_3 \). But, this contradicts the assumption that \( v(P, \{x_1, x_2, x_3\}) = v(P, \{x_1, x_2\}) \neq x_3 \).
P, the associated choice function \( v(P, \cdot) \) can be rationalized by a linear ordering. In turn, Independence of losing alternatives implies that majority rule determines the outcome on binary issues. In combination, these observations imply that, for each profile \( P \), the majority relation must be a linear ordering. While true for certain profiles, this is clearly not true for all profiles. To avoid this problem while preserving the connection to majority rule, the scope of Plott’s condition must be limited. Instead of being unaffected by every splitting of an issue, the outcome can only be unaffected by one such splitting (again see Claim 5 of the Appendix).

4 Marginalization on specialized formats

Rules for determining the order of voting on proposals have a significant impact on agenda structure. In this section, I define two classes of simple agendas, called priority agendas and convex agendas, whose structure is closely related to the most prevalent order-of-voting rules used in legislative settings. I then show that each class is characterized by the way that it marginalizes (or discriminates against) certain alternatives.

4.1 Priority agendas

Priority agendas share the same basic sequential structure as Euro-Latin and Anglo-American agendas: among the remaining alternatives, each question contests the two alternatives that have the highest priority.

Definition 6 A priority agenda on \( A \in X \) is a simple agenda, equipped with a linear ordering \( \succ \) on \( A \), such that, for every non-terminal node \( D \) of the agenda: \( x \succ y \succ z \) and \( x, y \in D \) imply \( z \in D \). In the sequel, I will refer to an ordering that satisfies this condition as a priority ordering for the agenda.

Without loss of generality, the priority \( \succ \) may be defined so that every question eliminates either: the remaining alternative that has the highest priority; or an interval of alternatives starting from the remaining alternative that has the second highest priority (see Remark 6 of the Appendix). Given a node \( D \), label the alternatives \( d_1, \ldots, d_k \in D \) according to \( \succ \) (so that \( d_i \succ d_j \) implies \( i < j \) for all \( d_i, d_j \in D \)). Then, for some index \( i^* \) such that \( 3 \leq i^* \leq k + 1 \), the agenda must sub-divide the issue \( D \) as in Figure 3 below.

\[
\begin{array}{c}
\{d_1, \ldots, d_k\} \\
\{d_1, d_{i^*}, \ldots, d_k\} & \{d_2, \ldots, d_k\}
\end{array}
\]

Figure 3: Structure of a priority agenda at a non-terminal node \( D \)

Among priority agendas, Euro-Latin and Anglo-American agendas define the two extremes. At each node of a Euro-Latin agenda, majority support for the highest priority alternative \( d_1 \) forecloses every other alternative.

\footnote{Simplicity imposes restrictions on the next highest priority alternative \( d_{i^*} \) that is reachable when the majority supports \( d_1 \). An earlier version of the paper defined priority agendas in an equivalent (but cumbersome) way that makes these restrictions explicit.}

\footnote{In case \( i^* = k + 1 \), the successors of \( D = \{d_1, \ldots, d_k\} \) are (the singleton) \( d_1 \) and the complementary issue \( \{d_2, \ldots, d_k\} \).}
reachable from that node (i.e., $i^* = k + 1$). For an Anglo-American agenda, majority support for the highest priority alternative $d_1$ only forecloses the second highest priority alternative $d_2$ (i.e., $i^* = 3$).

Priority agendas are closely related to the rule of precedence that many Anglo-American (and some European) legislatures use for voting on amendments. This rule states a new proposal must be put to vote before: (i) the proposal that it amends; and (ii) any subsequent amendment of the same proposal.

This rule typically induces a priority among the amended versions of the original proposal. In the textbook scenario with a proposal, an amendment to the proposal, an amendment to the amendment etc., the rule of precedence ensures that “more” amended versions of the proposal have priority over “less” amended versions. Depending on whether the more amended versions must then be put to vote against less amended versions, the agenda induced by this priority could be Euro-Latin or Anglo-American (Miller, 1995, pp. 13 and 18).

Example 1 illustrates another situation where the rule of precedence induces a priority among versions of the original proposal. This agenda gives highest priority to the amended bill $ba'$, intermediate priority to the amended bill $ba''$ and the original bill $b$, and lowest priority to the status quo alternative $\emptyset$. However, a slight variation of this example shows that the rule of precedence does not necessarily induce a priority.

**Example 5** When the two amendments $a'$ and $a''$ in Example 1 are compatible, a small change to the agenda occurs: $a''$ must be recognized regardless of whether $a'$ is adopted. This results in the following agenda.\footnote{As noted by Bach (1983, p.575), this rule is used by both houses of US Congress.} \footnote{While typically associated with the Anglo-American tradition, this rule is also used by some countries with a Euro-Latin legal tradition—including the Czech Republic (Zákon o jednacím řádu Poslanecké sněmovny, Article 72), Portugal (Regimento da Assembleia da República, Article 154), and Slovakia (Rokovací poriadok Národnej Slovenskej republiky, Article 37).}

- **Q1.** Shall the first amendment $a'$ to the bill $b$ be adopted?
- **Q2.** Shall the second amendment $a''$ to the bill $b$ be adopted?
- **Q3.** Shall the perfected bill replace the status quo $\emptyset$?

\[
\{ba', ba'', ba', b, \emptyset\} \\
\{ba'a'', ba', ba'', b, \emptyset\} \\
\{ba'a'', ba', \emptyset\} \\
ba'a'' \emptyset ba' \emptyset ba'' \emptyset b \emptyset
\]

Relative to Example 1, the only change is to allow for the “doubly” amended bill $ba'a''$. Somewhat surprisingly, the resulting agenda is not compatible with a priority. To see this, suppose that $b$ had highest priority. Then, the other versions of the bill must all appear in the other sub-tree below the root (as in Figure 3), which is not the case. Since the same argument holds for any version of the bill, the agenda is not prioritarian. Still, it...
is simple. Since every node has a unique label, it is history-independent. To see that it is also persistent, note that the status quo $\emptyset$ is the only uncontested alternative and it is always contested by the final question.

### 4.2 Convex agendas

Just like priority agendas, convex agendas are defined in terms of a linear ordering of the alternatives. The difference is that each question contests the two remaining alternatives that are furthest apart (or most "extreme") in terms of this ordering rather than the two that are most highly ranked.

**Definition 7** A **convex agenda** on $A \in X$ is a simple\(^{31}\) agenda, equipped with a linear ordering $\succ$ on $A$, such that, for every non-terminal node $D$ of the agenda: $x \succ y \succ z$ and $x, z \in D$ imply $y \in D$. In the sequel, I will refer to an ordering that satisfies this condition as a **convex ordering** for the agenda.

This definition implies that every question eliminates an interval of alternatives starting from one of the two extremes. For a given node $D = \{d_1, \ldots, d_k\}$ (with the alternatives labeled according to $\succ$), this means that the agenda must sub-divide the issue $D$ as in Figure 4 below for some $\hat{i}, \hat{j}$ such that $1 < \hat{j} \leq \hat{i} < k$.

![Figure 4: Structure of a convex agenda at a non-terminal node $D$](image)

Clearly, convexity rules out certain agenda formats. Anglo-American agendas, for instance, are convex only if they contain three or fewer alternatives.\(^{32}\) In contrast, all Euro-Latin agendas are convex: at any node, majority support for $d_1$ forecloses every other alternative while majority support against $d_1$ forecloses only $d_1$ itself. The convexity of Euro-Latin agendas follows from their knockout structure. Indeed, to define a convex ordering for any knockout agenda, it suffices to "read off" the terminal nodes from left to right.

A range of convex agendas besides knockout agendas arise in legislative settings. The reason is their close relationship to the **extremeness rule** that most European legislatures use for voting on proposals.\(^{33}\) Unlike the rule of precedence, this rule is primarily content-based. It orders proposals in terms of the “extremeness” of their departure from an established reference point (typically the original proposal or the status quo); and puts

---

\(^{31}\)The definition of Kleiner and Moldovanu (2017) is more general since it does not require the agenda to be simple.

\(^{32}\)To establish this point (which does not appear to be clearly appreciated in the literature), fix an Anglo-American agenda $T_A$ such that $|A| \geq 4$; and, index $A \equiv \{a_1, \ldots, a_k\}$ by an ordering that makes it prioritarian. By way of contradiction, suppose that there is another ordering $\succ_e$ that makes $T_A$ convex. Then, for the two nodes below the root (labeled $\{a_1, a_3, \ldots, a_k\}$ and $\{a_2, a_3, \ldots, a_k\}$), Figure 4 implies $a_1 \succ_e a_4 \succ_e a_3$ and $a_3 \succ_e a_4 \succ_e a_2$.

\(^{33}\)Besides countries with an Anglo-American legislative tradition (UK, Switzerland, and Sweden), some notable exceptions are the three countries (Czech Republic, Portugal, and Slovakia) mentioned in footnote 29 (Rasch, Table 2).
more extreme proposals to vote before less extreme ones.\footnote{See e.g., Article 30.2 of the German \emph{Geschäftsordnung des Bundesrates}: “...if several proposals are made to the same subject, then the first vote shall be on the farthest-reaching proposal. Decisive is the degree of deviation from status quo.”}

Since it imposes no restrictions on (the structure of) the convex ordering, Definition 7 is flexible enough to capture the various notions of extremeness used in different jurisdictions. In fact, it even captures agendas, like the agenda in Example 3, that are built by contesting the least extreme alternatives. (For this agenda, one convex ordering of the amendments is \(a_3 \succ a_4 \succ a_1 \succ a_2\).)

It is not difficult to show that a simple agenda with fewer than five alternatives must either be prioritarian or convex.\footnote{This is clear for agendas with three or fewer alternatives. It is also true for agendas with four alternatives. Up to permutation, there are nine simple agendas with four alternatives: four that are convex and prioritarian (the Euro-Latin agenda plus three others); two priority agendas that are not convex (the Anglo-American agenda and the one in Example 1); and, three convex agendas that are not prioritarian (the agendas in Examples 2 and 3 plus one other).} With more alternatives, a simple agenda need not respect either of these formats. Example 5 serves to illustrate. As explained, the agenda in this example is simple but not prioritarian. To see that it is not convex, simply note that any convex ordering \(\succ\) of the alternatives must put the status quo \(\emptyset\) between every pair of perfected bills in \(\{ba'a'', ba', ba'', b\}\). This is a contradiction.

Remark 2 Every simple agenda with four or fewer alternatives is either prioritarian or convex. However, there are simple agendas with more than four alternatives that do not respect either format.

4.3 Characterization

For Euro-Latin and Anglo-American agendas, Moulin (1988, p.250) showed that the lowest priority alternative is chosen only if it clearly appeals to the majority. Formally, an alternative \(a \in A\) is the Condorcet winner for the decision problem \((P, A) \in P \times X\) if \(aM_{P,x}\) for all \(x \in A \setminus a\). A decision rule \(\nu\) marginalizes \(a^* \in A\) on the issue \(A \in X\) if, for all profiles \(P \in P\), \(\nu(P, A) = a^*\) only if \(a^*\) is the Condorcet winner for \((P, A)\).

In fact, Euro-Latin and Anglo-American agendas can be distinguished from other simple agendas by the number of alternatives that they marginalize. For every issue consisting of three or more alternatives, Anglo-American agendas marginalize one alternative whereas Euro-Latin agendas marginalize two alternatives. (Intuitively, the difference comes down to the fact that the two alternatives with lowest priority are symmetrically placed in a Euro-Latin agenda but not an Anglo-American agenda.)

Theorem 2 A decision rule \(\nu\) is implementable by:

(a) Euro-Latin agenda if and only if it satisfies Issue splitting and Independence of losing alternatives, and, for every issue \(A \in X\) consisting of three or more alternatives, \(\nu\) marginalizes two alternatives.

(b) Anglo-American agenda if and only if it satisfies Issue splitting and Independence of losing alternatives, and, for every issue \(A \in X\) consisting of three or more alternatives, \(\nu\) marginalizes one alternative.

Despite the important structural differences between Euro-Latin and Anglo-American agendas, Theorem 2 shows that the two formats marginalize alternatives in a similar fashion. This result provides a counterpoint to
the work of Apesteguia et al. Instead of emphasizing fundamental similarities between the two formats, their characterizations (which I discuss in the Online Appendix) highlight some key differences.

More generally, marginalization may be used to characterize the voting outcomes associated with all priority agendas. Like a Euro-Latin or Anglo-American agenda, a priority agenda always marginalizes the lowest priority alternative. So, a decision rule implemented by such an agenda must satisfy the following condition:

**Marginalization** For every issue \( A \in X \), there is some alternative that \( v \) marginalizes on \( A \).

In fact, this condition is sufficient to distinguish priority agendas from all other simple agendas.

**Theorem 3** A decision rule \( v \) is implementable by priority agenda if and only if it satisfies Issue splitting, Independence of losing alternatives, and Marginalization.

Convex agendas can be characterized along similar lines. As Example 2 serves to illustrate, a convex agenda need not marginalize any alternatives. In fact, for issues consisting of four or more alternatives, a convex agenda only marginalizes one alternative in the interest of promoting another. To formalize, fix an issue \( A \in X \) where the decision rule \( v \) marginalizes alternative \( a_* \in A \). Then, \( v \) marginalizes \( a_* \) in favor of \( a^* \in A \setminus a_* \) on \( A \) if \( v(P, A) = a^* \) for some profile \( P \in P \) such that \( a_* M_P a^* \).

**Directed marginalization** For every issue \( A \in X \) consisting of four or more alternatives, each alternative \( a_* \in A \) that \( v \) marginalizes on \( A \) is in favor of some other alternative \( a^* \in A \).

This condition distinguishes convex agendas from all other simple agendas.

**Theorem 4** A decision rule \( v \) is implementable by convex agenda if and only if it satisfies Issue splitting, Independence of losing alternatives and Directed marginalization.

## 5 Monotonicity of simple agendas

May (1952) argued that a chosen alternative should continue to be chosen when it improves in terms of voters’ preferences.\(^{36}\) In this section, I show that all decision rules implemented by simple agenda satisfy this desirable monotonicity condition while decision rules implemented by agendas outside this class need not.

To formalize, let \( P^\uparrow x \) denote a profile where every voter’s preference is identical to profile \( P \) except for one voter, whose preference between \( x \) and the immediately preferred alternative (if any) is reversed. Thus, \( P^\uparrow x \) differs from \( P \) only by improving alternative \( x \) for a single voter. Then, a decision rule \( v \) is **monotonic** at the issue \( A \) if, for each profile \( P \in P \) and every profile \( P^\uparrow x \in P \), \( v(P, A) = x \) implies \( v(P^\uparrow x, A) = x \).

**Monotonicity** For every issue \( A \in X \), \( v \) is monotonic.

\(^{36}\)The normative appeal of this property should be clear. As a weak form of Maskin monotonicity, it also has practical appeal. In particular, it discourages certain kinds of voter misrepresentations (Sanver and Zwicker, 2009) as well as certain kinds of manipulations by the alternatives, which may represent candidates in an election (Altman, Procaccia, and Tennenholtz, 2009).
This condition translates May’s *Positive responsiveness* to the context of single-valued decision rules.\(^{37}\)

According to a folk result, every decision rule implemented by knockout agenda must be monotonic (see e.g., Moulin, 1988, p.285; or Altman et al., 2009). To see this, consider the “backward induction” path that leads to the outcome \(x\) being chosen for the problem \((P, X)\). Since each alternative appears only once in the agenda, the alternatives that \(x\) faces along this path cannot be affected by improving it. So, \(x\) remains the outcome for any problem \((P^{\uparrow x}, X)\). Moulin (1986, p.288) showed that this type of argument extends to Anglo-American agendas. Even though some alternatives appear more than once, improving the winner \(x\) cannot affect which alternatives it faces along a winning path. In fact, the same reasoning extends to all simple agendas:

**Theorem 5** Every decision rule \(v\) implementable by simple agenda satisfies Monotonicity.

Beyond the class of simple agendas, it is not difficult to identify non-monotonic decision rules.

**Example 6** Consider the non-persistent agenda on \(X = \{x_1, x_2, x_3, x_4, x_5\}\) depicted below (left).

The decision rule implemented by this agenda is non-monotonic. To see this, consider a profile \(P\) whose majority relation completes the partial relation \(MP\) depicted above (right). The sophisticated outcome at \(P\) is \(x_5\). However, when \(x_5\) improves by reversing the majority comparison with \(x_4\), the outcome changes to \(x_2\).

What makes the agenda in this example troubling is that it has two features common in legislative settings. It is non-repetitive: every question eliminates some potential outcomes.\(^{38}\)\(^{39}\) It is also continuous: for every question, some contested outcome continues to be contested until it is eliminated or eventually selected.\(^{40}\) Note that every simple agenda has these same two features (by Remark ?? of the Online Appendix).

---

\(^{37}\)May originally defined Positive responsiveness for social aggregation rules rather than social choice rules. When translated to the setting of (multi-valued) choice, May’s condition is usually understood to be stronger than Monotonicity. Conventionally, a (multi-valued) choice rule \(v : P \times X \rightarrow X\) is said to be positively responsive at \(A \in X\) if \(x \in v(P, A)\) implies \(v(P^{\uparrow x}, A) = \{x\}\); and monotonic at \(A \in X\) if \(x \in v(P, A)\) (only) implies \(x \in v(P^{\uparrow x}, A)\). See Horan et al. (2019) for a discussion.

\(^{38}\)An agenda is non-repetitive if, for every non-terminal node \(q, \ell(q) \neq \ell(q_i)\) for \(i = y, n\). This is Farquharson’s Axiom II.

\(^{39}\)The non-monotonic agenda proposed by Moulin (1986, p.284) lacks this feature.

\(^{40}\)An agenda is continuous if, for every non-terminal node \(q\) such that \(c(q_i) \neq \emptyset\) (for \(i = y, n\)), some alternative in \(c(q_i)\) labels exactly one terminal node below \(q_i\). Ordeshook and Schwartz (p.185) only defined this concept for “Ordeshook-Schwartz” agendas (see footnote 9). To adapt it to “Farquharson-Miller” agendas, Miller (1995, p.26) required every contested alternative to be contested until it is eliminated or selected. The weaker definition given here is closer to Groseclose and Krehbiel (1993).
Since the agenda in Example 6 is easily extended to more alternatives, we obtain the following:

**Remark 3** There are decision rules implemented by non-repetitive and continuous agendas that violate Monotonicity if (and only if) the universe of alternatives $X$ contains five or more alternatives.\(^{41}\)

This remark shows that non-repetitiveness and continuity are not sufficient for Monotonicity. The next example, which features an agenda sometimes used by US Congress, shows that the second feature is also unnecessary:

**Example 7** Both the House and the Senate have special procedures for parallel consideration of a bill and a substitute to the bill. When amendments to the original bill and substitute are proposed, the rules specify a “two-stage” agenda where the amendments are put to vote before deciding on the form of the bill.\(^{42}\)

\[
\begin{align*}
Q1. & \quad \text{Shall the amendment } a' \text{ to the original bill } b \text{ be adopted?} \\
Q2. & \quad \text{Shall the amendment } a'' \text{ to the substitute bill } s \text{ be adopted?} \\
Q3. & \quad \text{Shall the bill (as amended) be adopted over the substitute (as amended)?} \\
Q4. & \quad \text{Shall the perfected version of the bill be selected over the status quo } \emptyset? \\
\end{align*}
\]

Since this agenda is history-independent, it is non-repetitive (by Claim 9 of the Appendix). At the same time, it is also discontinuous: the second question shifts the focus from the amendment $a'$ of the original bill to the amendment $a''$ of the substitute bill.\(^{43}\) Nonetheless, it implements a monotonic rule.

**Remark 4** The agenda in Example 7 implements a decision rule that satisfies Monotonicity.

The proof leverages the fact that both sub-agendas below the root (i.e., starting from $\{ba', s, sa'', \emptyset\}$ and $\{b, s, sa''\}$) are simple. Yet, as Example 6 illustrates, not every agenda formed by joining two simple agendas at the root implements a monotonic decision rule. Indeed, as Example 7 suggests, the relative position of the alternatives that appear in both sub-agendas seems to play a crucial role.

\(\text{\quad}^{41}\text{Every non-repetitive and continuous agenda on } |X| \leq 4 \text{ alternatives implements a monotonic decision rule. So, the counter-example in Example 6 is minimal in terms of the number of alternatives (as well as the number of terminal nodes).}\)

\(\text{\quad}^{42}\text{See also Figure 2 of Ordeshook and Schwartz; Figure 2 of Banks, 1989; Figure 4 of Miller; or Figure 2 of Schwartz, 2008.}\)

\(\text{\quad}^{43}\text{Formally, } b \text{ and } ba' \text{ are contested at the root; but } s \text{ and } sa'' \text{ are contested at its two successors. This shows that the agenda is also non-persistent: the set of uncontested alternatives at the root } \{s, sa''\} \text{ does not label any node below the root.}\)
6 Conclusion

In the current paper, I introduce a broad class of agendas, called simple agendas, whose two defining features are common in legislative settings. My main result (Theorem 1) characterizes the rules implemented by simple agenda. I also show that all simple agendas exhibit a desirable monotonicity property (Theorems 5) originally proposed by May (1952). Finally, I characterize some specialized agenda formats in terms of the way that they deviate from neutrality by marginalizing certain alternatives (Theorems 2 to 4).

These results establish the connection between form and function for a wide range of agendas used in legislative settings. Ultimately, the goal is to provide insights that can be leveraged in applications. In companion work (Horan, 2019), I consider implications of my results for applications related to strategic candidacy (Dutta et al., 2001 and 2002) and competitive agenda-setting (Dutta et al., 2004; Duggan, 2006).

I close by mentioning a few questions raised by the results of the current paper. Given Theorems 2-4, one natural question is whether marginalization is equally important for other simple agenda formats (besides those considered here) that arise in legislative settings. In the Online Appendix, I discuss some progress on this question. Another natural question relates to monotonicity. More specifically, Theorem 5 and Remark 4 suggest that agendas used in legislative settings tend to implement monotonic decision rules. Ideally, one would hope to identify basic structural features of legislative agendas (even more fundamental than history-independence and persistence) that are sufficient for Monotonicity.

7 References


Radner, Roy and Jacob Marschak. 1954. “Note on Some Proposed Decision Criteria” in Thrall, Coombs, and Davis (Eds.), Decision Processes, New York: John Wiley and Sons.


Remark 5
For an agenda \(T\), the following are equivalent: (a) \(T\) is persistent; and, (b) for each node \(q\) of \(T\) such that \(u(q) \neq \emptyset\) and every node \(q'\) below \(q\) such that \(\ell(q') \supset u(q)\), either: (i) \(\{\ell(q'), \ell(q_n)\} = \{\ell', u(q)\}\); or, (ii) \(\{\ell(q'), \ell(q_n)\} = \{\ell', \ell''\}\) for \(\ell', \ell'' \supset u(q)\).

Note: For ease of presentation in the sequel, I refer to the property specified in (b) above as Property (*).

Proof. (a \(\Rightarrow\) b) Fix a node \(q'\) below \(q\) such that \(\ell(q') \supset u(q)\) \(\neq \emptyset\). By Persistence, \(u(q) \subseteq \ell(q_p)\) or \(\ell(q_n)\). Otherwise, there is no node between \(q\) and a terminal node \(t\) below \(q'\) with a successor labeled by \(u(q)\). If \(u(q) = \ell(q_p)\) or \(\ell(q_n)\), then case (i) of Property (*) obtains. Otherwise, \(\ell(q_p), \ell(q_n) \supset u(q)\) so that case (ii) obtains.

(b \(\Rightarrow\) a) The proof is by strong induction on \(|X| \equiv m\). The base cases \(m = 2, 3\) are trivial. To complete the induction, suppose that the claim holds for \(m \leq n\) and consider \(m = n + 1\). Let \(q^1\) and \(q^1_n\) denote the successors of the
root \( r \) in \( T \). Note that the sub-trees \( T(q_1^1) \) and \( T(q_8^1) \) inherit Property (*) from \( T \). So, \( T(q_1^1) \) and \( T(q_8^1) \) are persistent by the induction hypothesis. So, \( T \) is persistent at every non-terminal node, with the possible exception of \( r \).

To check persistence at \( r \), suppose that \( u(r) \neq \emptyset \). Consider a terminal node \( t \) below \( q_9^1 \) and (without loss of generality) let \( q_9^1, \ldots, q_9^t = t \) denote the path from \( q_9^1 \) to \( t \). By Property (*), there are two possibilities for the successors of \( q_9^t \): (i) \( \ell(q_9^t) = \ell' \), \( u(r) \); and (ii) \( \ell(q_9^t), \ell(q_9^t) = \ell'' \) for \( u(r) \in \ell', \ell'' \). In case (i), \( q_9^t \) is a node between \( r \) and \( t \) with a successor labeled \( u(r) \). In case (ii), consider the node \( q_9^t \). Since \( u(r) \in \ell(q_9^t) \in \ell(q_9^t) \), one can repeat the same argument for \( q_9^t \). Since \( T \) is finite, it follows that one of the nodes \( q_9^t \) between \( r \) and \( t \) must have a successor labeled \( u(r) \). Since the same argument holds for any terminal node \( t' \) below \( q_8^4 \), \( T \) is persistent at \( r \).

### 8.4 Proof of Theorem 1

Subsection 1 establishes sufficiency, while subsections 2 and 3 establish necessity and uniqueness, respectively.

#### 8.4.1 Sufficiency

**Claim 1** For \( A = B \cup C \), the following are equivalent: (a) \( B \cap C \neq A \); (b) \( B \cap C \neq B \cup C \); and, (c) \( B \cap C \neq B \cup C \).

**Proof.** (a) \( \Rightarrow \) (b): Suppose that \( B \cap C = B \). Then, \( C = (B \cap C) \cup C = B \cup C = A \) which is a contradiction. (b) \( \Rightarrow \) (c): Suppose that \( B \cap C = \emptyset \). Then, \( B = (B \cap C) \cup (B \cap C) = (B \cap C) \cup C = B \cup C \) which is a contradiction. (c) \( \Rightarrow \) (a): Suppose that \( B = A \). Then, \( C \cap B = C \cap A = \emptyset \) which is a contradiction.

**Note:** For each of Claims 2-8, I assume that \( \nu \) satisfies IS and ILA.

**Claim 2** If \( P, P' \in P \) coincide on \( A \in X \), then \( \nu(P, A) = \nu(P', A) \).

**Proof.** The proof is by induction on \( |A| \). The case \( |A| = 2 \) follows from ILA. So, suppose that the claim holds for \( |A| = n \) and consider \( |A| = n + 1 \). Let \( (B, C) \) denote the splitting of \( A \). Then, IS, the induction hypothesis, and the base case imply \( \nu(P, A) = \nu(P, \{v(P, B), v(P, C)\}) = \nu(P, \{v(P', B), v(P', C)\}) = \nu(P', \{v(P', B), v(P', C)\}) = \nu(P', A) \).

**Claim 3** If \( A \in X \) and \( P^A \) is as defined in Remark 1, then \( \nu(P, A) = \nu(P^A, X) \).

**Proof.** By ILA, \( \nu(P^A, X) = \ldots = \nu(P^A, A) \). Since \( \nu(P^A, A) = \nu(P, A) \) by Claim 2, \( \nu(P^A, X) = \nu(P, A) \).

**Claim 4** If \( (B, C) \) splits \( A \in X \) and \( D \subset A \), then: (i) \( \nu(P, D) = \nu(P, \{v(P, B \cap D), v(P, C \cap D)\}) \); and, (ii) \( (B \cap D, C \cap D) \) splits \( D \) if \( D \neq B \cap D, C \cap D \).

**Proof.** Fix \( x \in A \) and let \( (B, C) \) denote the splitting of \( A \). Let \( P^X \setminus x \) coincide with \( P \) except that \( x \) is demoted to the bottom of each voter’s preference. Then, \( \nu(P, A \setminus x) = \nu(P^X \setminus x, A \setminus x) = \nu(P^X \setminus x, A) = \nu(P^X \setminus x, \{v(P^X \setminus x, B), v(P^X \setminus x, C)\}) = \nu(P, \{v(P, B \setminus x), v(P, C \setminus x)\}) \) by Claim 2, ILA, and IS. Part (i) follows by repetition of this reasoning. For part (ii), observe that \( D \neq B \cap D, C \cap D \) implies \( B \cap C \cap D = B \cap D, C \cap D \) by Claim 1. So, \( (B \cap D, C \cap D) \) splits \( D \) by part (i).

**Claim 5** Every issue \( A \in X \) has a unique \( \nu \)-splitting.

**Proof.** The proof is by induction on \( |A| \). The case \( |A| = 2 \) is obvious. For the case \( |A| = 3 \), Table 1 shows that every exact bi-cover of \( A \) yields a distinct pair of outcomes on the two Condorcet triples. So, the splitting must be unique.
Now, suppose that the claim holds for $|A| = n$ and consider $|A| = n + 1$. By way of contradiction, suppose that $(B, C)$ and $(B', C')$ are distinct splittings of $A$. If both partition $A$, then there is some $x \in A$ such that $(B \setminus x, C \setminus x)$ and $(B' \setminus x, C' \setminus x)$ are distinct partitions of $A \setminus x$. Then, by Claim 4(ii), this contradicts the induction hypothesis. So, suppose that $x \in B \cap C$ for some $x \in A$. If $x \in B' \cap C'$, then $(B \setminus x, C \setminus x)$ and $(B' \setminus x, C' \setminus x)$ are distinct splittings of $A \setminus x$ by Claim 4(ii), which again contradicts the induction hypothesis. Finally, suppose that $x \in B' \setminus C'$. There are two possibilities for $(B \setminus x, C \setminus x)$ and $(B' \setminus x, C' \setminus x)$: either (i) they coincide; or, (ii) they are distinct.

(i) Suppose that $B \setminus x = B' \setminus x$ and $C \setminus x = C'$. (The reasoning is symmetric for $B \setminus x = C'$ and $C \setminus x = B' \setminus x$.) Since $(B, C)$ splits $A$, there exist $b \in B \setminus C$ and $c \in C \setminus B$. Since $B \setminus x = B' \setminus x$ and $C \setminus x = C'$, $b \in B' \setminus C'$ and $c \in C' \setminus B'$. Letting $D = \{b, c, x\}$ gives distinct splittings $(B \cap D, C \cap D) = (\{x, b\}, \{x, c\})$ and $(B' \cap D, C' \cap D) = (\{x, b\}, \{c\})$ by Claim 4(ii), which contradicts the base case of the induction.

(ii) First, suppose that $B' \setminus C' \neq x$. Then $(B \setminus x, C \setminus x)$ and $(B' \setminus x, C' \setminus x)$ are distinct splittings of $A \setminus x$ by Claim 4(ii), which contradicts the induction hypothesis. Next, suppose that $B' \setminus C' = x$. Since $(B, C)$ splits $A$, there exist alternatives $b \in B \setminus C$ and $c \in C \setminus B$. Letting $D = \{b, c, x\}$ gives $(B \cap D, C \cap D) = (\{x, b\}, \{x, c\})$, $x \in B' \setminus C'$, and $b, c \in C'$. So: (a) $(B' \cap D, C' \cap D) = (\{x\}, \{b, c\})$; (b) $(B' \cap D, C' \cap D) = (\{x\}, \{b, c\})$; or, (c) $(B' \cap D, C' \cap D) = (\{x, b\}, \{b, c\})$. Sub-cases (a)-(b) yield splitting of $D$ the differ from $(B \cap D, C \cap D)$, which contradicts the base case of the induction by Claim 4(ii). Finally, case (c) yields a contradiction. By Claim 4(i),

$$v(P_{bcx}, D) = v(P_{bcx}, \{v(P_{bcx}, B' \cap D), v(P_{bcx}, C' \cap D)\}) = v(P_{bcx}, \{v(P_{bcx}, D), v(P_{bcx}, \{b, c\})\}).$$

The solution is $v(P_{bcx}, D) = b$. But, $v(P_{bcx}, D) = v(P_{bcx}, \{v(P_{bcx}, B \cap D), v(P_{bcx}, C \cap D)\}) = c$ as well. ■

Claim 5 makes it possible to define a simple agenda for a decision rule $v$. Let $S_{\{x, y\}}$ denote the unique simple agenda with two terminal nodes labeled $x$ and $y$; and, $S_{\{x\}}$ denote the unique degenerate agenda with a single node labeled $x$.

**Definition 8** Given a decision rule $v$ that satisfies IS and ILA, the agenda $S^v$ is defined as follows:

1. First, define $S'(1) \equiv S_{\{X\}}$ (to be the degenerate agenda whose only node is labeled $X$).
2. Then, for each $j > 1$, define the agenda $S^v(j + 1)$ from $S^v(j)$ as follows:
   - For each terminal node labeled by a non-singleton $A$ (if any), determine its $v$-splitting $(B_A, C_A)$ and,
   - Replace every terminal node of $S^v(j)$ labeled by $A$ with the simple agenda $S_{\{B_A, C_A\}}$.
3. Finally, define $S^v \equiv S^v(|X| - 1)$.

Figure 5 below illustrates the recursive construction of $S^v$. The leftmost nodes below $B_X$ illustrate the construction for $|A| = 2$ while the leftmost nodes below $C_X$ illustrate it for $|A| > 2$. In turn, the two triangles represent the subgames starting from the nodes labeled $C_{B_X}$ and $C_{C_X}$ while the ellipses indicate where details have been omitted.\(^{44}\)

\(^{44}\)It is important not to confuse the agenda $S(A)$ with the agenda $S|A$. While the former refers to the subgame at node $A$ in $S$, the latter refers to the pruned agenda on $A$ obtained from $S$. As Figure 2 illustrates, these agendas may be quite different.
By construction, the agenda \( S^v \) is history-independent. The next three claims show that it is also persistent:

**Claim 6** If \( (B, C) \) splits \( A \in X \) and \( (B', C') \) splits \( D \in X \) for \( \emptyset \subset B \cap C \subset D \subset C \), then \( B \cap C \subset B' \) or \( B \cap C \subset C' \).

**Proof.** By way of contradiction, suppose that \( B \cap C \not\subset B' \), \( C' \). Fix alternatives \( b \in (B \cap C) \setminus C' \) and \( c \in (B \cap C) \setminus B' \). Since \( B \cap C \subset D \), there exists some \( d \in D \setminus (B \cap C) \). Up to symmetry, there are two cases: (i) \( d \in B' \cap C' \); and, (ii) \( d \in B' \setminus C' \). Since \( (B, C) \) splits \( A \), \( v(P, \{b, c, d\}) = v(P, \{v(P, \{b, c\}), v(P, \{b, c, d\})\}) \) by Claim 4(i).

I show that both cases (i) and (ii) entail a contradiction. (i) Since \( (B', C') \) splits \( D \), Claim 4(i) implies

\[
v(P, \{b, c, d\}) = v(P, \{v(P, B' \cap \{b, c, d\}), v(P, C' \cap \{b, c, d\})\}) = v(P, \{v(P, \{b, d\}), v(P, \{c, d\})\}).
\]

So, \( v(P_{bcd}, \{b, c, d\}) = c \) for the Condorcet triple \( P_{bcd} \). Combining this with the formula in the last paragraph gives

\[
c = v(P_{bcd}, \{b, c, d\}) = v(P_{bcd}, \{v(P_{bcd}, \{b, c\}), v(P_{bcd}, \{b, c, d\})\}) = v(P_{bcd}, \{b, c\}) = b.
\]

(ii) The reasoning is similar to case (i). Since \( (B', C') \) splits \( D \), Claim 4(i) implies \( v(P, \{b, c, d\}) = v(P, \{v(P, \{b, d\}), c\}) \). So, \( v(P_{bcd}, \{b, c, d\}) = c \). Combining this with the formula before case (i) gives \( c = v(P_{bcd}, \{b, c, d\}) = b \).

**Claim 7** If \( (B, C) \) splits \( A \in X \) and \( (B', C') \) splits \( D \in X \) for \( \emptyset \subset B \cap C \subset D \subset C \) and \( B \cap C \not\subset B' \), then \( B \cap C = C' \).

**Proof.** Since \( B \cap C \not\subset B' \), \( B \cap C \subset C' \) by Claim 6. By way of contradiction, suppose that \( B \cap C \subset C' \). Fix alternatives \( b \in B' \setminus C' \), \( c \in (B \cap C) \setminus B' \), and \( d \in C' \setminus (B \cap C) \). Since \( B \cap C \subset C' \), \( b \in B' \setminus (B \cap C) \). There are two cases: (i) \( d \in B' \cap C' \); and, (ii) \( d \in C' \setminus B' \). Since \( (B, C) \) splits \( A \), \( v(P, \{b, c, d\}) = v(P, \{v(P, \{b, c\}), v(P, \{b, c, d\})\}) \) by Claim 4(i). For cases (i) and (ii), this entails a contradiction for \( v(P_{bcd}, \{b, c, d\}) \). The reasoning is similar to the proof of Claim 6.

**Claim 8** If \( (B, C) \) splits \( A \in X \) and \( \emptyset \subset B \cap C \subset D \subset C \), then either: (i) \( (B', B \cap C) \) splits \( D \) for some \( B' \subset D \); or, (ii) \( (B', C') \) splits \( D \) for some \( B', C' \supseteq B \cap C \).

**Proof.** Let \( (B', C') \) denote a splitting of \( D \). Given Claims 6 and 7, (i) and (ii) are the only possibilities for \( (B', C') \).

**Lemma 1** \( S^v \) defines a simple agenda.
**Proof.** By Claim 5, the construction in Definition 8 is well-defined. Since \( v \) satisfies IS, the construction is finitary and, thus, defines an agenda \( S^v \). By construction, the agenda \( S^v \) is history-independent. From Claim 8 and Definition 8, it follows that \( S^v \) also satisfies Property (\(*\)) (which is defined after Remark 5). So, \( S^v \) is persistent by Remark 5. ■

Given Lemma 1, it remains to show that \( S^v \) implements \( v \).

**Lemma 2** \( S^v \) implements \( v \).

**Proof.** The proof is by strong induction on \(|X| = m\). The base cases \( m = 2, 3 \) follow from IS and the definition of \( S^v \).

To complete the induction, suppose that the claim holds for \( m \leq n \) and consider \( m = n + 1 \).

Given Claim 3 and Remark 1, it suffices to show that \( v(P, X) = SVO[S^v; P] \) for all \( P \in P \).

To show this, let \( B \) and \( C \) denote the successors of the root \( X \) in \( S^v \). Consider the restricted decision rules \( v_B \) and \( v_C \) that coincide with \( v \) on \( B \) and \( C \), respectively. By the induction hypothesis, \( S^v_B \) implements \( v_B \) and \( S^v_C \) implements \( v_C \). Since \( S^v(B) = S^v_B \) and \( S^v(C) = S^v_C \) by construction, \( v_B(P, B) = SVO[S^v(B); P] \) and \( v_C(P, C) = SVO[S^v(C); P] \). Since \( v \) selects the Condorcet winner between two alternatives (by ILA), “backward induction” requires \( SVO[S^v; P] = v(P, \{v_B(P, B), v_C(P, C)\}) \). Then, by definition of \( v_B \) and \( v_C \), \( SVO[S^v; P] = v(P, \{v(P, B), v(P, C)\}) \). Since \( (B, C) \) splits \( X \), \( v(P, \{v(P, B), v(P, C)\}) = v(P, X) \). Combining these observations gives

\[
 v(P, X) = v(P, \{v(P, B), v(P, C)\}) = SVO[S^v; P].
\]

■

**Proof of Theorem 1 (Sufficiency).** By Lemmas 1 and 2. ■

### 8.4.2 Necessity

The argument given in the main text shows the necessity of ILA. The following claims establish the necessity of IS:

**Claim 9** Every history-independent agenda is non-repetitive.

**Proof.** Fix a history-independent agenda \( T \) and consider a non-terminal node \( q \) where \( B \equiv \ell(q) \). By way of contradiction, suppose that \( \ell(q_n) = B \) and \( \ell(q_n) \equiv C \subseteq B \). By history-independence, the successors of \( q \) are labeled \( B \) and \( C \). Repeating this argument, there is a countably infinite path down the agenda from \( q \) where every node is labeled by \( B \). This contradicts the finiteness of \( T \). ■

**Claim 10** If \( S \) is a simple agenda where \( B \) and \( C \) are the two successors of the root \( X \), then:

\[
 SVO[S; P] = x \in B \cap C \text{ implies } SVO[S(B); P] = x = SVO[S(C); P].
\]

**Proof.** The proof is by strong induction on \(|X| = m\). By Claim 9, \( S \) is non-repetitive. So, the base cases \( m = 2, 3 \) are trivial. To complete the induction, suppose that the claim holds for \( m \leq n \) and consider \( m = n + 1 \). By way of contradiction, suppose that \( SVO[S; P] = SVO[S(B); P] \equiv xMPC \equiv SVO[S(C); P] \).

First, consider \( S(B) \). Since \( S \) is simple, so is \( S(B) \). By persistence, every path to a terminal node \( t \) below \( B \) passes through a node \( B_t \) (potentially \( B \) itself) with successors \( B_t \) and \( B \cap C \). Let \( T(B, x) \equiv \{t : x \in B_t\} \). There are two cases:

(i) \( T(B, x) = \emptyset \); and,
(ii) \( T(B, x) \neq \emptyset \). (i) Since \( SVO[S(B); P] = x \) and \( x \notin B_t \) for all \( t \) below \( B \), “backward induction” requires \( SVO[S(B \cap C); P] = x \).

(ii) Since \( SVO[S(B); P] = x \), “backward induction” requires \( SVO[S(B_t); P] = x \) for some \( t \in T(B, x) \). Since \( S(B_t) \) is simple and \( |B_t| \leq n \), the induction hypothesis implies \( SVO[S(B \cap C); P] = x \).

---

\(^{45}\)To see this, fix some \((P, A) \in P \times X\). Since \( v(P, A) = v(P^A, X) \) (by Claim 3) and \( SVO[S^v; P^A] = SVO[S^v[A]; P] \) (by Remark 1), showing \( v(P^A, X) = SVO[S^v[A]; P^A] \) establishes \( v(P, A) = v(P^A, X) = SVO[S^v; P^A] = SVO[S^v[A]; P] \) for all \((P, A) \in P \times X\).
Next, consider $S(C)$. If $c \in B \cap C$, the same reasoning as in the last paragraph establishes $SVO[S(B \cap C); p] = c$, a contradiction. So, $c \in C \setminus B$. By persistence, every path to a terminal node $t$ below $C$ passes through a node $C_i$ (potentially $C$ itself) with successors $C_i$ and $B \cap C$. Let $T(C, c) \equiv \{ t : c \in C_i \}$. By construction, $T(C, c) \neq \emptyset$. Since $SVO[S(C); p] = c$, “backward induction” requires $SVO[S(C_i); p] = c$ for some $t \in T(C, c)$. Since $SVO[S(B \cap C); p] = \chi$ and $x M_p c$ however, $SVO[S(C_i); p] = \chi$. So, $SVO[S(C_i); p] \neq c$ by “backward induction,” a contradiction.

\textbf{Claim 11} If $S$ is a simple agenda where $B$ and $C$ are the successors of the root $X$, $SVO[S|B; p] = SVO[S(B); p]$.

\textbf{Proof.} If $B \cap C = \emptyset$, then $S|B = S(B)$ by definition and the claim follows. So, suppose that $B \cap C \neq \emptyset$. Fix a profile $P \in P$ such that $SVO[S|B; p] = b$. By Remark 1, $SVO[S; P^B] = b$. Since $P$ and $P^B$ coincide on $B$, the proof is complete if $SVO[S(B); P^B] = b$. In that case, $SVO[S(B); p] = b = SVO[S|B; P]$. To establish $SVO[S(B); P^B] = b$, there are two cases: (i) $b \in B \setminus C$; and, (ii) $b \in B \cap C$. (i) Since $b \in B \setminus C$, “backward induction” requires $SVO[S(B); P^B] = b$. (ii) Since $SVO[S; P^B] = b \in B \cap C$, Claim 10 implies $SVO[S(B); P^B] = b$.

\textbf{Lemma 3} If a decision rule $v$ is implementable by simple agenda, then it satisfies IS.

\textbf{Proof.} Suppose that $v$ is implemented by $S$. The proof is by strong induction on $|X| \equiv m$. By Claim 9, $S$ is non-repetitive. So, the base cases $m = 2, 3$ are trivial. To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. Let $B$ and $C$ denote the successors of the root $X$; and, fix an issue $A$ with three or more alternatives. Up to symmetry, there are two possibilities: (a) $A \not\subset B, C$; or, (b) $A \subset B$.

(a) In this case, $(B \cap A, C \cap A)$ splits $A$. That is, it satisfies conditions (i)-(iii) of the definition. (i) Since $B \cup C = X$, $(B \cap A) \cup (C \cap A) = (B \cup C) \cap A = X \cap A = A$. (ii) By contradiction, suppose that $B \cap C = (B \cap A) \cap (C \cap A)$. Then, $A = (B \cap A) \cup (C \cap A) = [(B \cap A) \cap (C \cap A)] \cup (C \cap A) = C \cap A$. So, $A \subset C$ which is a contradiction. (iii) Note that $v(P, B) \equiv SVO[S|B; p] = SVO[S(B); P]$ and $v(P, C) \equiv SVO[S|C; p] = SVO[S(C); P]$ by Claim 11. Since $v(P, X) \equiv SVO[S; p]$ as well, “backward induction” requires $v(P, X) = v(P, \{v(P, B), v(P, C)\})$. Combined with Remark 1, this identity implies the following:

\[
v(P, A) = v(P, A, X) = v(P, \{v(P, B), v(P, C)\}) = v(P, \{v(P, B \cap A, X), v(P, C \cap A, X)\})
\]

\[
= v(P, \{v(P, B \cap A), v(P, C \cap A)\}) = v(P(v(P, B \cap A), v(P, C \cap A), X))
\]

(b) By Claim 11, $v(P, B) \equiv SVO[S|B; p] = SVO[S(B); P]$. Then, by Remark 1, $S(B)$ implements the restricted decision rule $v_B$ that coincides with $v$ on $B$. Since $S$ is non-repetitive by Claim 9, $B \subset C$ so that $|B| \leq n$. Since $S$ is simple, so is $S(B)$. By the induction hypothesis, it then follows that $v_B$ has a splitting for $A$. So, suppose that $(A_B, C_A)$ splits $A$ for $v_B$. Since $v_B(P, D) \equiv v(P, D)$ for all $D \in B$, $(A_B, C_A)$ also splits $A$.

8.4.3 Uniqueness

\textbf{Lemma 4} If $v$ satisfies IS and ILA, then $S^v$ is the unique simple agenda that implements $v$.

\textbf{Proof.} The proof is by strong induction on $|X| \equiv m$. The base cases $m = 2, 3$ follow from IS. To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$.

Fix a simple agenda $S$ that implements $v$; and, let $B$ and $C$ denote the two successors of the root $X$ in $S$. First, note that $(B, C)$ is the (unique) splitting of $X$. To see this, it is enough to check conditions (i)-(iii) in the definition of
a splitting. (i) Since $S$ is an agenda, $B \cup C = X$. (ii) Since $S$ is non-repetitive by Claim 9, $B, C \neq B \cap C$ by Claim 1. (iii) By Claim 11, $SVO[S; P] = SVO[S(B); P]$ and $SVO[S; C] = SVO[S(C); P]$ for all $P \in P$. Since $S$ implements $v$, $v(P, B) = SVO[S; P]$ and $v(P, C) = SVO[S; C]$. So, $v(P, B) = SVO[S(B); P]$ and $v(P, C) = SVO[S(C); P]$. Since $v(P, X) = SVO[S; P]$ as well, $v(P, X) = v(P, \{v(P, B), v(P, C)\})$.

Next, consider the restricted rules $v_B$ and $v_C$ that coincide with $v$ on $B$ and $C$, respectively. As shown in the last paragraph, $v_B(P, B) = SVO[S(B); P]$ and $v_C(P, C) = SVO[S(C); P]$ for all $P \in P$. So, $S(B)$ implements $v_B$ and $S(C)$ implements $v_C$ by Remark 1 and Claim 3. Since $S$ is simple, so are $S(B)$ and $S(C)$. By the induction hypothesis, $S_B^v$ (resp. $S_C^v$) is the unique simple agenda that implements $v_B$ (resp. $v_C$). So, $S_B^v = S(B)$ and likewise $S_C^v = S(C)$. Since $(B, C)$ is the unique splitting of $X$ (as shown in the last paragraph), the definition of $S'$ implies $S = S'$.

**Lemma 5** If $v$ satisfies IS and ILA, then the structure of $S'$ is determined by the outcomes of $v$ on Condorcet triples.

**Proof.** Fix an issue $A$ such that $|A| > 2$. For any sub-issue $\{x, b, c\} \subseteq A$, there are three potential splittings where $b$ and $c$ appear in separate sub-issues: (a) $\{(b, x), (c, x)\}$, (b) $\{(b, c, x)\}$, and (c) $\{(b, x), c\}$. Each of these implements a different combination of outcomes on the two Condorcet triples:

<table>
<thead>
<tr>
<th>Profile \ Agenda</th>
<th>(a)</th>
<th>(b)</th>
<th>(c)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$P_{xbc}$</td>
<td>$c$</td>
<td>$b$</td>
<td>$c$</td>
</tr>
<tr>
<td>$P_{xcb}$</td>
<td>$b$</td>
<td>$b$</td>
<td>$c$</td>
</tr>
</tbody>
</table>

Outcomes: Majority loser between $b$ and $c$, Outcome $b$ for both triples, Outcome $c$ for both triples.

Table 1: Outcomes implemented by (a)-(c).

Let $(B_A, C_A)$ denote the unique splitting of $A$. By construction, there exist alternatives $b_A \in B_A \setminus C_A$ and $c_A \in C_A \setminus B_A$. Then, the outcomes of $v$ on each issue $\{x, b_A, c_A\}$ involving an alternative $x \in A$ must coincide with one of the possibilities in Table 1. This observation may be used to pin down alternatives $b_A, c_A \in A$ (perhaps non-uniquely). Again using Table 1, one can then describe the unique splitting $(B_A, C_A)$ of $A$ in terms of Condorcet triples. In particular:

$$B_A \equiv \{b_A\} \cup \{x \in A \setminus \{b_A, c_A\} : \text{the outcomes on } \{x, b_A, c_A\} \text{ are type-(a) or type-(c)}\}; \quad \text{and}$$

$$C_A \equiv \{c_A\} \cup \{x \in A \setminus \{b_A, c_A\} : \text{the outcomes on } \{x, b_A, c_A\} \text{ are type-(a) or type-(b)}\}.$$

It follows that the unique splitting of $A$ is determined by the outcomes of $v$ on Condorcet triples. ■

### 8.5 Proof of Theorem 2

**Note:** For each of the Claims 12-14 below, I assume that $v$ satisfies IS and ILA.

**Claim 12** If $a_x$ is marginal for $A \in X$ and $x \in A \setminus a_x$, then $a_x$ is marginal for $A \setminus x$.

**Proof.** Fix some $x \in A \setminus a_x$. By way of contradiction, suppose that $v(P, A \setminus x) = a_x$ for some profile $P$ where $a_x$ is not the Condorcet winner in $A \setminus x$. By Claim 2, $v(P, A \setminus x) = v(P, A \setminus x)$ for any profile $P^{X \setminus x}$ that coincides with $P$ except $x$ is denoted to Condorcet loser in $X$. Moreover, $v(P^{X \setminus x}, A) = v(P^{X \setminus x}, A \setminus x)$ by ILA. So, $v(P^{X \setminus x}, A) = a_x$, which contradicts the assumption that $a_x$ is marginal for $A$. ■
Claim 13 Every $A \in X$ has at most two marginal alternatives.

Proof. Suppose otherwise. Denote any three marginal alternatives in $A$ by $x$, $y$, and $z$ and consider the Condorcet triple $P_{xyz}$ (as defined in the text). Then, $v(P_{xyz}, \{x, y, z\}) \notin \{x, y, z\}$ by Claim 12, which is a contradiction.

Claim 14 Suppose that $(B, C)$ splits $A \in X$ where $|A| > 2$ and $a_*$ is marginal for $A$. Then: (i) if $a_* \in C \setminus B$, then $(B, C) = (b, A \setminus b)$ for some $b \neq a_*$; and, (ii) if $a_* \in B$ and $a_*$ is also marginal for $A$, then $a_* \in B$.

Proof. (i) By way of contradiction, suppose that $|B \setminus C| \geq 2$. Fix $b, b' \in B \setminus C$ and consider the triple $P_{a, bb'}$. By Claim 4, the splitting of $\{a_*, b, b'\}$ is $\{(b, b'), a_*\}$; and, $v(P_{a, bb'}, \{a_*, b, b'\}) = v(P_{a, bb'}, \{v(P_{a, bb'}, \{b, b'\}), a_*\}) = a_*$. By Claim 12, this contradicts the assumption that $a_*$ is marginal for $A$. (ii) By way of contradiction, suppose that $a_* \in C \setminus B$. Without loss of generality, $|A| > 2$ implies there is some alternative $x \in A$ such that: $x \in B \setminus C$ if $a_* \in B \cap C$; or, $x \in B$ if $a_* \in B \setminus C$. In either case, a contradiction obtains along the same lines as (i).

Claim 15 Suppose that $v$ satisfies IS and ILA. (i) If each $A \in X$ such that $|A| > 2$ has two marginal alternatives, then $S^v$ is Euro-Latin. (ii) If each $A \in X$ such that $|A| > 2$ has one marginal alternative, then $S^v$ is Anglo-American.

Proof. Consider the splitting $(B, C)$ of $X$ and let $x_*$ denote an alternative that is marginal on $X$.

(i) By Claim 14, the potential splittings of $X$ are: (1) $(B, C) = (b_1, X \setminus b_1)$ for $x_* \neq b_1$; and, (2) $x_* \in B \cap C$ with $b \in B \setminus C$ and $c \in C \setminus B$. For (2), Claim 4(ii) implies that $\{x_*, b, c\}$ has one marginal alternative $x_*$, which is a contradiction. So, the splitting must be (1). Continuing in the same vein on $X \setminus b_1$ shows that $S^v$ is Euro-Latin.

(ii) If $|C \setminus B| \geq 1$ (with $b \in B \setminus C$ and $c, c' \in C \setminus B$), then Claim 4(ii) implies that $c$ and $c'$ are marginal on $\{b, c, c'\}$, which is a contradiction. Since $|B \setminus C| \geq 1$ yields a similar contradiction, $(B, C) = (X \setminus c_1, X \setminus b_1)$ for some $b_1 \in B \setminus x_*$ and $c_1 \in C \setminus x_*$ by Claim 14(i). Continuing in the same vein on $X \setminus c_1$ and $X \setminus b_1$ shows that $S^v$ is Anglo-American.

Proof of Theorem 2. (Sufficiency) By Claim 15 and Theorem 1. (Necessity) It is clear that Euro-Latin and Anglo-American agendas are simple. By Theorem 1, a decision rule implemented by an agenda of either format must satisfy IS and ILA. Finally, for all issues $A$ such that $|A| > 2$, observe that: (a) every rule implemented by Euro-Latin agenda marginalizes the last two alternatives in the priority ordering (which are symmetric); and, (b) every rule implemented by Anglo-American agenda marginalizes the last alternative in the priority ordering. (See Moulin, 1988, p.250.)

8.6 Proof of Theorem 3

Claim 16 If $q$ is a non-terminal node of a priority agenda $Pr$ such that $|\ell(q)| > 2$, then $\ell(q_r) = \ell(q) \setminus d$ or $\ell(q_n) = \ell(q) \setminus d$ where $d$ is one of the two highest priority alternatives at $q$.

Proof. Label the alternatives $\ell(q) = \{d_1, ..., d_k\}$ according to a priority ordering $\succ$ for $Pr$. If $d_1, d_2 \in \ell(q_r)$, then $\ell(q_r)$ must also contain every alternative with lower priority. So, $\ell(q_r) = \ell(q)$. But, this contradicts the fact that $Pr$ is non-repetitive. (Since it is a priority agenda, $Pr$ must be history-independent. By Claim 9, it must be also be non-repetitive). Without loss of generality, suppose $d_1 \in \ell(q_r) \setminus \ell(q_n)$. If $d_3 \in \ell(q_r)$, then $\ell(q_r) = \ell(q) \setminus d_2$ by definition of priority agendas. Similarly, $\ell(q_n) = \ell(q) \setminus d_3$ if $d_3 \in \ell(q_n)$.

Given a priority agenda $Pr_A$, let $\succ^p_A$ denote any ordering on $A$ that satisfies the following requirement: for all $a \in A$, there is a node in $Pr_A$ labeled $\{d \in A : d \not\succ^p_A a\}$. By Claim 16, there is some such ordering for each priority agenda.
Remark 6 If $Pr_A$ is a priority agenda, then every node takes the form in Figure 3 for $\succ^p_A$.

Proof. The proof is by strong induction on $|A| \equiv m$. The base cases $m = 2, 3$ are straightforward. To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. Label the alternatives in $A = \{a_1, \ldots, a_m\}$ according to $\succ^p_A$. Then, the successors of $A$ are $B \equiv \{a_1, a_2, \ldots, a_m\}$ and $C \equiv \{a_2, \ldots, a_m\}$. So, the root node takes the desired form for $\succ^p_A$. Since $T_B(B)$ and $T_A(C)$ are priority agendas, the induction hypothesis implies that every node starting from $B$ (respectively $C$) takes the desired form for $\succ^p_B$ (respectively $\succ^p_C$).

Since $Pr_A$ is non-repetitive and persistent, one successor of $B$ must contain $a_1$ while the other must be $\{a_1, \ldots, a_m\}$. So, $\succ^p_B$ may be taken to coincide with $\succ^p_A$ on $B$ (by defining $a_1 \succ^p_B b$ for all $b \in \{a_1, \ldots, a_m\}$ and letting $\succ^p_B$ to coincide with $\succ^p_A$ on $B \setminus a_1$). By construction, $\succ^p_C$ is the restriction of $\succ^p_A$ to $C$. $lacksquare$

Claim 17 If $v$ satisfies IS, ILA, and Marginalization, then $S^v$ is a priority agenda.

Proof. By Theorem 1, $S^v$ is simple. I show that there is some priority ordering $\succ$ for $S^v$. The proof is by induction on $|A| \equiv m$. The base cases $m = 2, 3$ are straightforward.

To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. By Marginalization, there is some marginal alternative $x_v$ on $X$. Consider any issue $A \in X$ such that $|A| > 2$ and $x_v \in A$. By Claim 12, $x_v$ is also marginal on $A$. Let $(B, C)$ denote the splitting of $A$. By Claims 4 and 14, $(B \setminus x_v, C \setminus x_v)$ splits $A$. It follows that $X \setminus x_v = S^v_{X \setminus x_v}$ (i.e., the restriction of $S^v$ to $X \setminus x_v$ coincides with the agenda on $X \setminus x_v$, built using Definition 3).

By the induction hypothesis, $S^v_{X \setminus x_v}$ is a priority agenda. Let $\succ^*$ denote a priority ordering for $S^v_{X \setminus x_v}$ and let $\succ$ denote the extension to $X$ where $x \succ x_v$ for all $x \in X \setminus x_v$. I show that $\succ$ is a priority ordering for $S^v$. Clearly, $\succ$ has the desired properties for any non-terminal node $A$ such that $x_v \notin A$ or $|A| = 2$. So, consider any node $A$ such that $x_v \in A$ and $|A| > 2$. By Claim 14, the splitting of $A$ must be: (i) $(b, A \setminus b)$ for some $b \neq x_v$; or (ii) $(B, C)$ with $|B|, |C| \geq 2$ and $x_v \in B \cap C$. The corresponding node $A \setminus x_v$ in $S^v_{X \setminus x_v}$ has the splitting (i) $(b, A \setminus \{b, x_v\})$ or (ii) $(B \setminus x_v, C \setminus x_v)$. Since $\succ^*$ has the desired properties for $A \setminus x_v$ in $S^v_{X \setminus x_v}$, it follows that $\succ$ has the desired properties for $A$ in $S^v$.

Proof of Theorem 3. (Sufficiency) By Claim 17 and Theorem 1. (Necessity) Suppose that $v$ is implemented by a priority agenda $Pr$ where the alternatives of $X \equiv \{x_1, \ldots, x_m\}$ are indexed by the priority ordering $\succ$. Since $Pr$ is simple by definition, Theorem 1 implies that $v$ satisfies IS and ILA.

To show that $v$ satisfies Marginalization, it suffices to show that $x_m$ is marginal for $X$. The proof is by strong induction on $m$. The base cases $m = 2, 3$ are straightforward. To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. Without loss of generality, the successors of $X$ are $B \equiv \{x_1, x_2, \ldots, x_m\}$ and $C \equiv \{x_2, \ldots, x_m\}$. So, $Pr(B)$ and $Pr(C)$ are priority agendas (with priorities that restrict $\succ$ to $B$ and $C$). By Claim 10, $SVO[Pr; P] = x_m$ only if $SVO[Pr(B); P] = x_m = SVO[Pr(C); P]$. Since $x_m$ is the lowest priority alternative in $B$ and $C$, the induction hypothesis implies that $SVO[Pr(B); P] = x_m = SVO[Pr(C); P]$ only if $x_m$ is the Condorcet winner on $(P, B)$ and $(P, C)$. In that case, $x_m$ must also be the Condorcet winner on $(P, X)$.

8.7 Proof of Theorem 4

Note: For each of the Claims 18-20 below, I assume that $v$ satisfies IS and ILA.

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46In fact, one can show that there are no such nodes where $x_v \notin A$ and $|A| > 2$.

47By Remark 1, it follows that $x_m$ is marginal for any issue $A \subseteq X$ such that $x_m \in A$. Since the pruned agenda $Pr|_{X'}$, on $X' \equiv \{x_1, \ldots, x_{m-1}\}$ is a priority agenda (with a priority that restricts $\succ$ to $X'$), the same argument shows that $x_{m-1}$ is marginal for any issue $A \subseteq X'$ such that $x_{m-1} \in A$. By progressively deleting the highest index alternative among those remaining and repeating this argument, it follows that there exists a marginal alternative for all $A$ such that $|A| > 2$. 

32
Claim 18 The following are equivalent: (a) \( v \) satisfies Directed marginalization; and (b) for all \( A \in X \) such that \( |A| = 4 \), no \( x_s \in A \) is uniquely marginal for all \( D \subset A \) such that \( |D| = 3 \) and \( x_s \in D \).

Note: For ease of presentation in the sequel, I refer to the property specified in (b) above as Property (**).

Proof. (a \( \Rightarrow \) b) Towards a contradiction, suppose that \( A = \{ x_s, y, z, w \} \) violates Property (**), with respect to \( x_s \in A \). Since \( v_A \) (i.e., the restriction of \( v \) to \( A \)) satisfies IS and ILA, Theorem 1 implies that \( v_A \) is implemented by simple agenda. For any pair of alternatives \( a, b \in \{ y, z, w \} \), the splitting of \( \{ x_s, a, b \} \) is then \( (\{ x_s, a \}, \{ x_s, b \}) \). Up to symmetry, this leaves two possibilities for the splitting of \( A \): (i) \( (A \setminus z, A \setminus y) \); and (ii) \( (\{ x_s, y \}, A \setminus y) \).

(i) In this case, IS implies:

\[
v(P, A) = v(P, \{ v(P, \{ v(P, \{ x_s, y \}), v(P, \{ x_s, z \}) \}), v(P, \{ v(P, \{ x_s, z \}), v(P, \{ x_s, w \}) \}) \}).
\]

So, \( x_s \) is marginal for \( A \) but none of the alternatives \( y, z, w \) is prioritized, which contradicts Directed marginalization.

(ii) In this case, IS implies:

\[
v(P, A) = v(P, \{ v(P, \{ v(P, \{ x_s, y \}), v(P, \{ v(P, \{ x_s, z \}), v(P, \{ x_s, w \}) \}) \}).
\]

As in the previous case, \( x_s \) is marginal for \( A \) but none of \( y, z, w \) is prioritized, which contradicts Directed marginalization.

(b \( \Rightarrow \) a) It suffices to verify that \( v \) does not violate Directed marginalization for any issue \( A \) such that \( |A| = 4 \). To see this, fix some issue \( B \) such that \( |B| > 4 \) with a marginal alternative \( x_s \in B \). By Claim 12, \( x_s \) is marginal for every issue \( x_s \in A \subset B \) such that \( |A| = 4 \). Suppose that \( v(P, A) = a^* \) for some profile \( P \) such that \( x, M_p a^* \) (i.e., \( v \) prioritizes \( a^* \) for \( A \)). Then, \( v(P^A, B) = a^* \) by Claim 3. What is more, \( x, M_p a^* \). So, \( v \) prioritizes \( a^* \) for \( B \).

To complete the proof, fix an issue \( A \) such that \( |A| = 4 \) with a marginal alternative \( x_s \in A \). By way of contradiction, suppose that \( v \) does not prioritize any alternative for \( A \). Since \( v_A \) (i.e., the restriction of \( v \) to \( A \)) satisfies IS, ILA and Marginalization, Theorem 3 implies that \( v_A \) is implemented by a priority agenda. Labeling the alternatives \( A = \{ a_1, \ldots, a_4 \} \) (in terms of priority), there are six possible priority agendas on \( A \). The only two that prioritize nothing for \( A \) are:

\[
\begin{align*}
\{ a_1, a_2, a_3, a_4 \} & \quad \{ a_1, a_2, a_3, a_4 \} \\
\{ a_1, a_4 \} & \quad \{ a_2, a_4 \} \\
\{ a_2, a_3 \} & \quad \{ a_3, a_4 \} \\
\end{align*}
\]

In either case, \( a_4 \) is uniquely marginal on \( \{ a_i, a_j, a_k \} \) for all distinct \( i, j \in \{ 1, 2, 3 \} \). So, \( v \) violates Property (**) on \( A \).

Claim 19 Suppose that \( v \) satisfies Directed marginalization. If \( (B, C) \) splits \( A \in X \) and \( B \cap C \neq \emptyset \), then \( (B', B \cup C) \) splits \( B \) and \( (B \cap C, C') \) splits \( C \) for issues \( B' \subset B \) and \( C' \subset C \) such that \( B' \cap C' = \emptyset \).

Proof. The proof is by strong induction on \( |B \cap C| = m \). For the base case \( m = 1 \), the claim is trivial if \( |A| = 3 \). So, suppose \( |A| \geq 4 \). Let \( (B_C, C_C) \) denote the splitting of \( C \) and define \( B \cap C \equiv \{ x \} \). By way of contradiction, suppose that \( B_C, C_C \neq \{ x \} \). By Claim 8, \( x \in B_C \cap C_C \). Since \( |A| \geq 4 \), there are \( b' \in B_C \setminus (B \cup C) \) and \( c' \in C_C \setminus (B \cup C) \). Since \( (B, C) \) splits \( X \), there is some \( b \in B \setminus C \). Since \( x \in B, B_C, C_C \), it follows that \( x \) violates Property (**) on
$A \equiv \{ x, b, b', c' \}$. By Claim 18, this contradicts Directed marginalization. So, the splitting of $C$ is $(x, C \setminus x)$. Since the same reasoning shows that the splitting of $B$ is $(B \setminus x, x)$, this establishes the base case.

To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. Fix some $x \in B \cap C$ and set $Y \equiv X \setminus x$. By Claim 4(ii), the splitting of $Y$ is $(B \setminus x, C \setminus x)$. By the induction hypothesis, the splittings of $B \setminus x$ and $C \setminus x$ are $(B', (B \cap C) \setminus x)$ and $((B \cap C) \setminus x, C')$ with $B' \cap C' = \emptyset$. By Claims 4(i) and 6, it follows that the splitting of $C$ is $(B \cap C, C'')$ with $C'' = C' \cup x$. By way of contradiction, suppose that $C'' = C' \cup x$. Fix alternatives $b \in B \setminus C$, $b' \in (B \cap C) \setminus C''$ and $c' \in C'' \setminus B$. By the same reasoning as in the base case, $x$ violates Property $(\ast \ast)$ on $A \equiv \{ x, b, b', c' \}$. So, the splitting of $C$ is $(B \cap C, C')$. Similarly, the splitting of $B$ is $(B', B \cap C)$. ■

Claim 20 If $v$ satisfies Directed marginalization, then $S'$ is convex.

Proof. The proof is by strong induction on $|X| \equiv m$. The base cases $m = 2, 3$ are trivial. For $m = 4$, Directed marginalization only rules out the two agendas in Claim 18. The seven remaining simple agendas on four alternatives are convex.

To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. Let $B$ and $C$ denote the successors of $X$. By the induction hypothesis, there are convex orderings $\succ_B$ and $\succ_C$ for $S'(B)$ and $S'(C)$, respectively. Given Claim 19, it suffices to show that $\succ_B$ and $\succ_C$ may be chosen so that they agree on $B \cap C$.

First, consider the splitting $(B \cap C, C')$ of $C$ and, suppose that $B \cap C' \neq \emptyset$. (Otherwise, no conflict between $\succ_B$ and $\succ_C$ need arise. In particular, there is a convex ordering $\succ_C$ on $C$ for $S'(C)$ that agrees with $\succ_B$ on $B \cap C$ and $\succ_C$ on $C'$.) By Claim 19, it follows that the splitting of $B \cap C$ is $(B \cap C', C'')$. Likewise, suppose $B' \cap C \neq \emptyset$ for the splitting $(B', B \cap C)$ of $B$. Then, the splitting of $B \cap C$ is $(B'', B' \cap C)$. Combining these observations implies that the splitting of $B \cap C$ is $(B' \cap C, B \cap C')$. What is more, $(B' \cap C) \cap (B \cap C') = \emptyset$ by Claim 19.

Up to right-left symmetry, there are two possibilities for any pair $x, y \in B \cap C$: (i) $x \in B' \cap C$ and $y \in B \cap C'$; or, (ii) $x, y \in B' \cap C$. (i) Fix alternatives $b \in B \setminus C$ and $c \in C \setminus B$. Up to right-left symmetry, the convexity of $S'(B)$ and $S'(C)$ implies $b \succ_B x \succ_B y$ and $x \succ_C y \succ_C c$. So, $\succ_B$ and $\succ_C$ need not disagree on the ranking of $x, y \in B \cap C$. (ii) As in case (i), there need be no conflict between $\succ_B$ and $\succ_C$. In particular, there is a convex ordering $\succ_C$ for $S'(C)$ that agrees with $\succ_B$ on $B \cap C'$ and agrees with $\succ_C$ on $C \setminus B' = C'$. ■

Proof of Theorem 4. (Sufficiency) By Claim 20 and Theorem 1. (Necessity) Suppose that $v$ is implemented by a convex agenda $\text{Conv}$ with ordering $\succ$. Since $\text{Conv}$ is simple, Theorem 1 implies that $v$ satisfies IS and ILA.

To show that $v$ satisfies Directed marginalization, it suffices to show that it satisfies Property $(\ast \ast)$ by Claim 18. Fix an issue $A \equiv \{ a_1, a_2, a_3, a_4 \}$ indexed by $\succ$. By definition of convex agendas, there is some node $A' \supseteq A$ with successors $B'$ and $C'$ such that $a_1 \in B' \setminus C'$ and $a_4 \in C' \setminus B'$. By Claim 4(ii), the splitting of $A$ must respect $\succ$ in the sense of Figure 4. Up to left-right symmetry, there are four possibilities: (i) $\{ \{ a_1, a_2, a_3 \}, \{ a_4 \} \}$; (ii) $\{ \{ a_1, a_2 \}, \{ a_3, a_4 \} \}$; (iii) $\{ \{ a_1, a_2, a_3 \}, \{ a_3, a_4 \} \}$; and, (iv) $\{ \{ a_1, a_2, a_3 \}, \{ a_2, a_3, a_4 \} \}$. For cases (i)-(iii), Claim 4(ii) implies that no alternative in $A$ violates Property $(\ast \ast)$. For cases (iii)-(iv), it suffices to check that $a_3$ does not violate Property $(\ast \ast)$. (The other alternatives are covered by Claim 4(ii) and/or symmetry.) For case (iii), Claim 4(i) requires the splitting of $\{ a_1, a_2, a_3 \}$ to be $\{ \{ a_1, a_2 \}, \{ a_3 \} \}$. So, $a_3$ is not even marginal for $\{ a_1, a_2, a_3 \}$. For case (iv), Claim 4(i) requires the splitting of $\{ a_1, a_2, a_3 \}$ to be $\{ \{ a_1, a_2 \}, \{ a_2, a_3 \} \}$ or $\{ \{ a_1, a_2 \}, \{ a_2, a_3 \} \}$. In either case, $a_3$ is not uniquely marginal for $\{ a_1, a_2, a_3 \}$. ■

8.8 Proof of Theorem 5 and Remark 4

Proof of Theorem 5. Suppose that the decision rule $v$ is implemented by a simple agenda $S$. It suffices to show that $v$ is monotonic at $X$. (Since $v(P, A) = v(P^A, X)$ by Remark 1, the result follows for all $A \in X$. The proof is by strong
induction on $|X| \equiv m$. The base cases $m = 2, 3$ are trivial. To complete the induction, suppose that the claim holds for $m \leq n$ and consider $m = n + 1$. Let $B$ and $C$ denote the successors of the root $X$ in $S$. For a profile $P$ such that $v(P, X) = SVO[S; P] = x$, there are two cases: (i) $x \in B \cap C$; and, (ii) $x \in B \setminus C$.

(i) By Claim 10, $SVO[S(B); P] = SVO[S(C); P] = x$. Since $S$ is non-repetitive by Claim 9, $B, C \subseteq X$ so that $|B|, |C| \leq n$. Since $S$ is simple, so are $S(B)$ and $S(C)$. By the induction hypothesis, it follows that $SVO[S(B); P^{\uparrow x}] = x = SVO[S(C); P^{\uparrow x}]$. Then, "backward induction" requires $v(P^{\uparrow x}, X) = SVO[S; P^{\uparrow x}] = x$.

(ii) By the same reasoning as case (i), $SVO[S(B); P^{\uparrow x}] = SVO[S(B); P] = x$. Moreover, $SVO[S(C); P^{\uparrow x}] = SVO[S(C); P]$ since $x \notin C$. Then, "backward induction" requires $v(P^{\uparrow x}, X) = SVO[S; P^{\uparrow x}] = x$. ■

**Proof of Remark 4.** First, observe that the agendas $A' \equiv A(\{ba', s, sa'', \varnothing\})$ and $A'' \equiv A(\{b, s, sa'', \varnothing\})$ below the root node of the agenda $A$ in Example 7 are simple. So, $A'$ and $A''$ satisfy Monotonicity by Theorem 5. Letting $SVO[A; P] \equiv x$, there are three cases: (a) $x \in \{b, ba'\}$; (b) $x \in \{s, sa''\}$; and, (c) $x = \varnothing$.


(b) Let $x = s$. Since $s$ appears in both sub-agendas at the root, there are two cases:

(i) If $SVO[A'; P] = s = SVO[A''; P]$, then $SVO[A'; P^{\uparrow s}] = s = SVO[A''; P^{\uparrow s}]$. By Monotonicity of $A'$ and $A''$. So, "backward induction" implies $SVO[A; P^{\uparrow s}] = s$.

(ii) If $SVO[A'; P] \neq s = SVO[A''; P]$, then $SVO[A''(\{b, s, \varnothing\}); P] = s$ so that $sMPs$. Since $A'$ is simple, $SVO[A'; P] = ba'$ (resp. $\varnothing$) implies $SVO[A'(\{ba', s, \varnothing\}); P] = ba'$ (resp. $\varnothing$) by Claim 10. So, $SVO[A'; P] = sa''$. (If $SVO[A'; P] = ba'$, then $SVO[A'(\{ba', s, \varnothing\}); P] = ba'$ so that $ba'MPs$, which contradicts $SVO[A; P] = s$. If $SVO[A'; P] = \varnothing$, then $\varnothingMPs$, which is a contradiction.) Since $SVO[A'; P] = sa''$, $SVO[A'(\{ba', sa'', \varnothing\}); P] = sa''$. In turn, this implies $SVO[A'(\{ba', s, \varnothing\}); P] = ba'$ (since $sMPsa''$ and $\varnothing$). So, $ba'MPs$ and $ba'MP\varnothing$. So, $SVO[A'(\{ba', s, \varnothing\}); P^{\uparrow s}] = s$ (since $sMP\varnothing$); and, $SVO[A'; P^{\uparrow s}] = s$ (since $SVO[A'(\{ba', sa'', \varnothing\}); P^{\uparrow s}] = sa''$ and $sMPsa''$). Since $SVO[A''; P^{\uparrow s}] = s$ by Monotonicity of $A'$, $SVO[A; P^{\uparrow s}] = s$.

(c) Since $\varnothing$ is available in every terminal sub-game, it is the Condorcet winner on $P$. So, $SVO[A; P^{\uparrow s}] = \varnothing$. ■